

Applications of Matched Filtering for Improved Interferometric Imaging and Weak Line Detection

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Collaborators: K. Öberg, S. Andrews, C. Walsh, I. Czekala, J. Huang



Improvements with new interferometers

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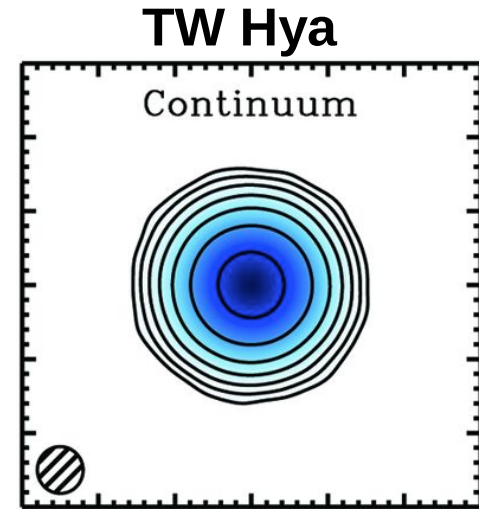
- Spatial resolution

Improvements with new interferometers

- Spatial resolution
- Sensitivity

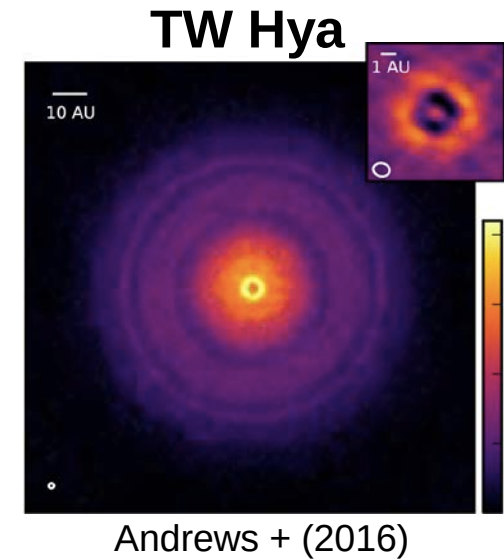
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- Spatial resolution
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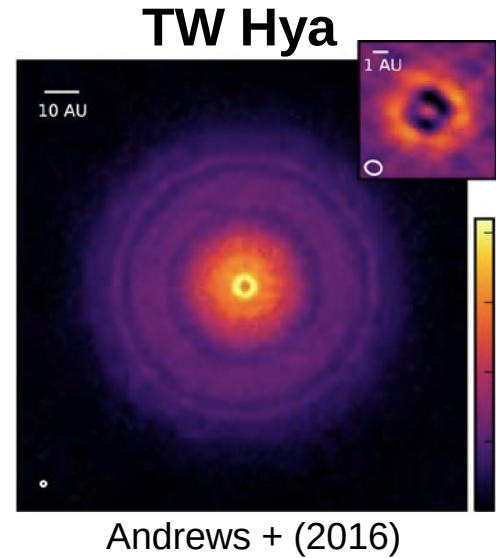
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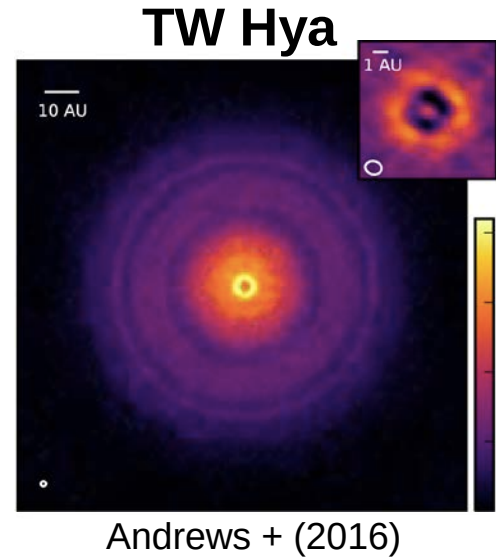
Improvements with new interferometers

- Spatial resolution
- Sensitivity
- Bandwidth



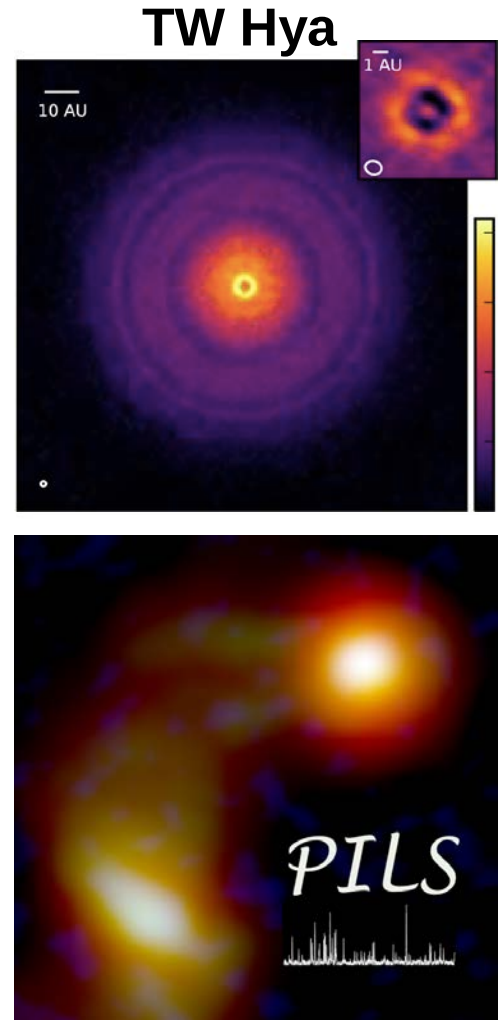
Improvements with new interferometers

- Spatial resolution
- Sensitivity
- Bandwidth
- Spectral resolution



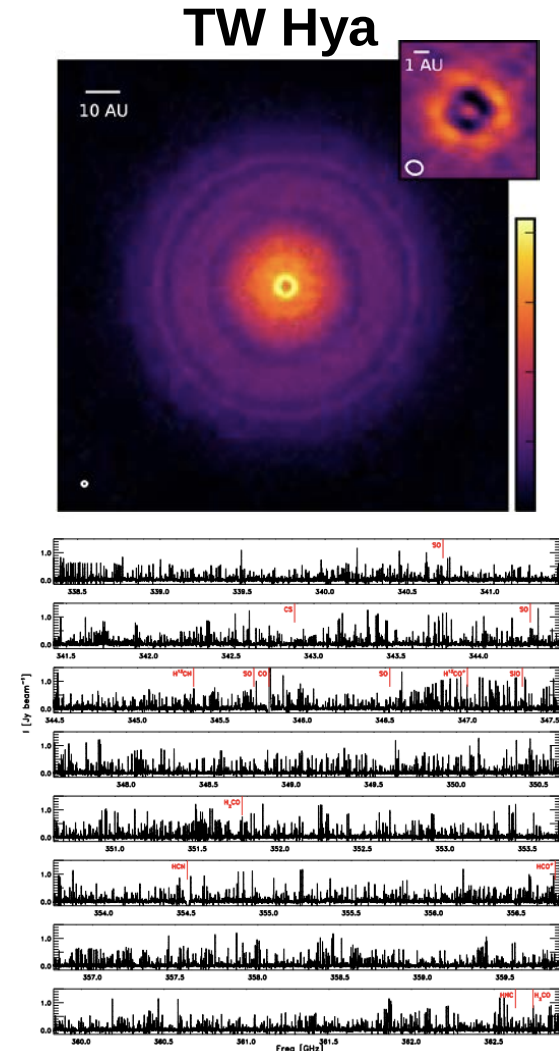
Improvements with new interferometers

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Improvements with new interferometers

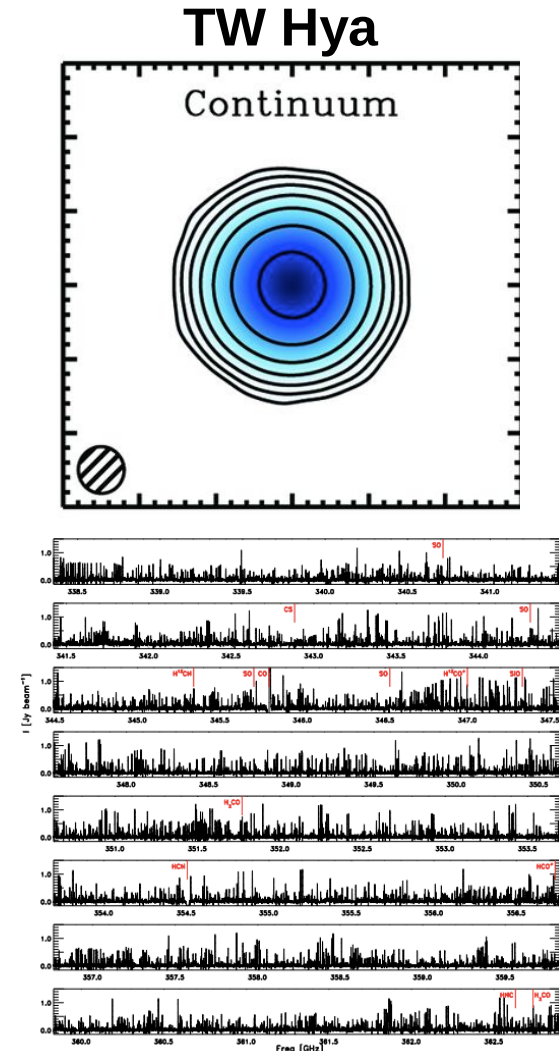
- Spatial resolution
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- Spectral resolution



Jorgensen + (2016)

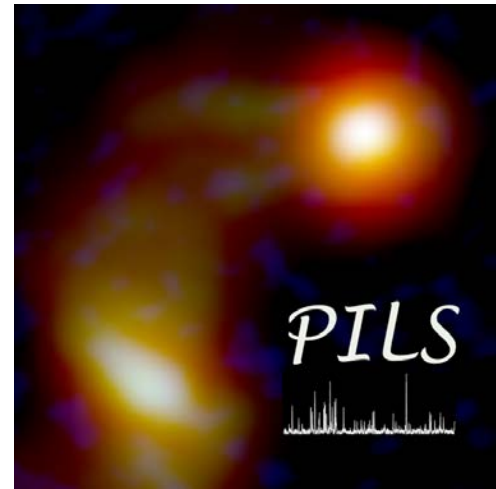
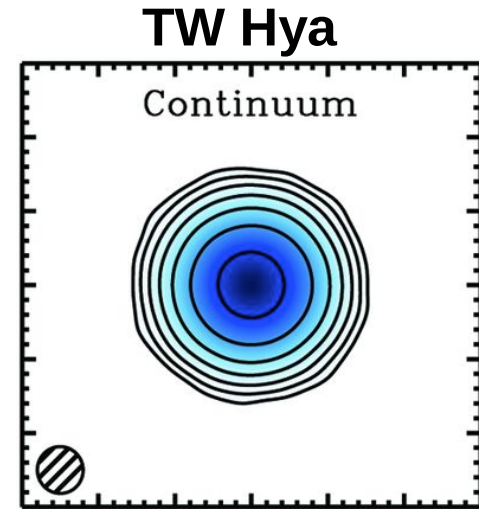
Point source assumptions

- Spatial resolution
- Sensitivity
- Bandwidth
- Spectral resolution



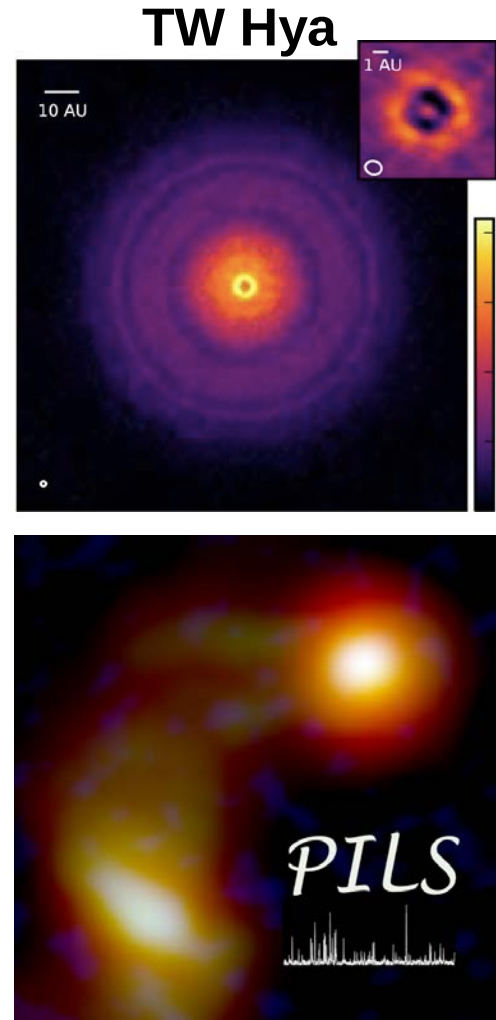
Point source assumptions

- Spatial resolution
- Sensitivity
- Bandwidth
- Spectral resolution



Opportunities for improved techniques

- Spatial resolution
- Sensitivity
- Bandwidth
- Spectral resolution

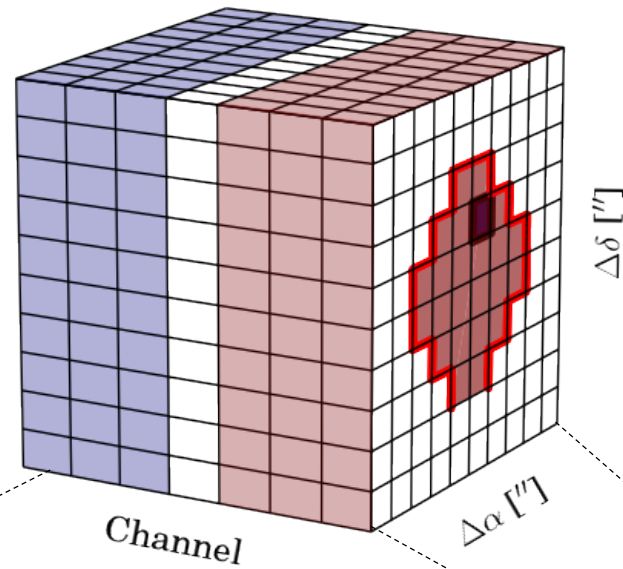


Outline

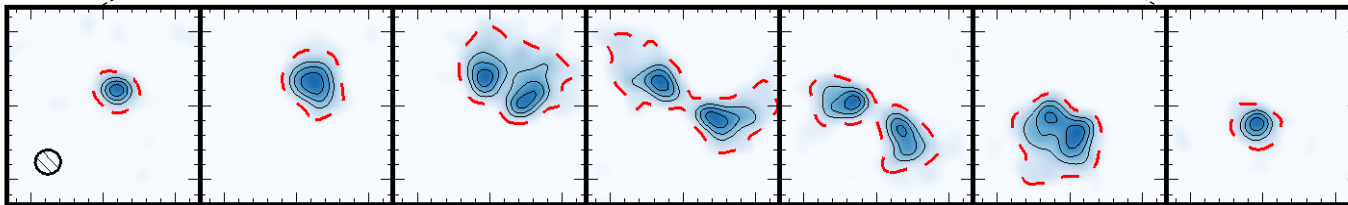
- Matched filtering for improved weak spectral line detection
- Generalized Briggs weighting for improved image fidelity

Analyzing imaged observations

Image Cube



Channel Map



[Loomis + 2018]

Analyzing imaged observations

Moment Maps

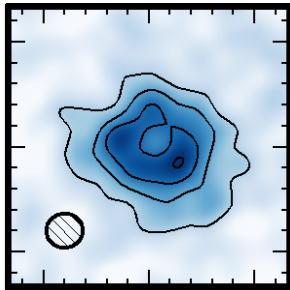
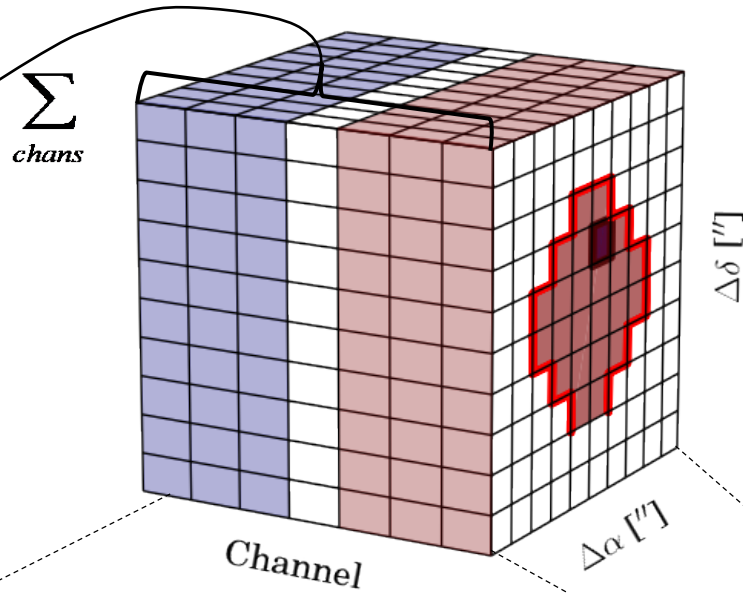
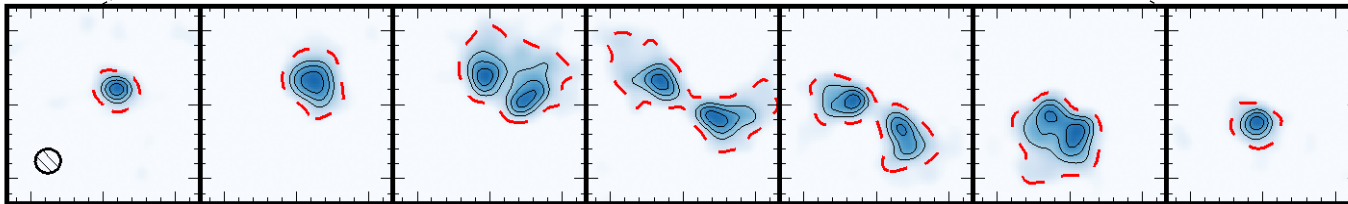


Image Cube

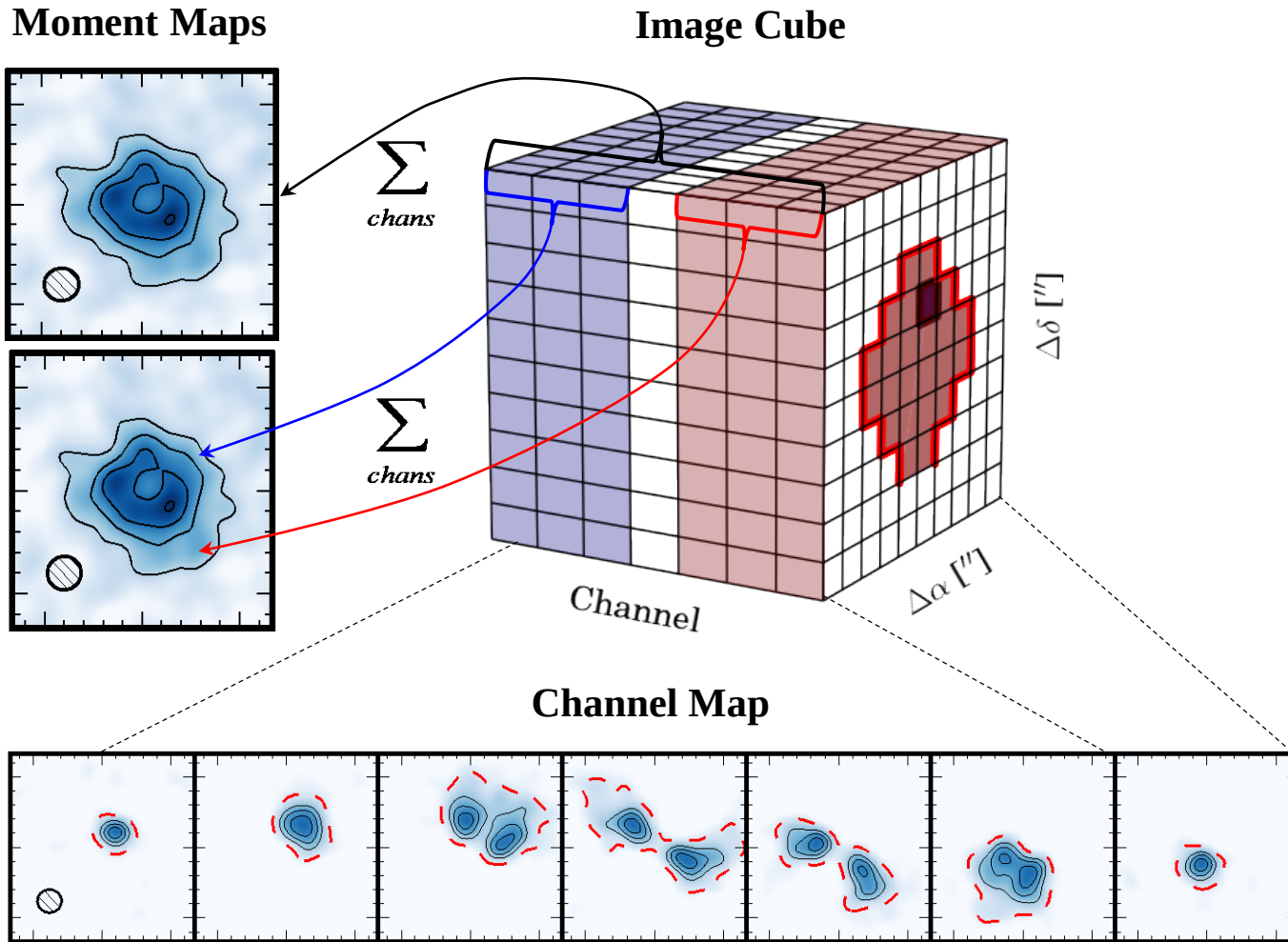


Channel Map



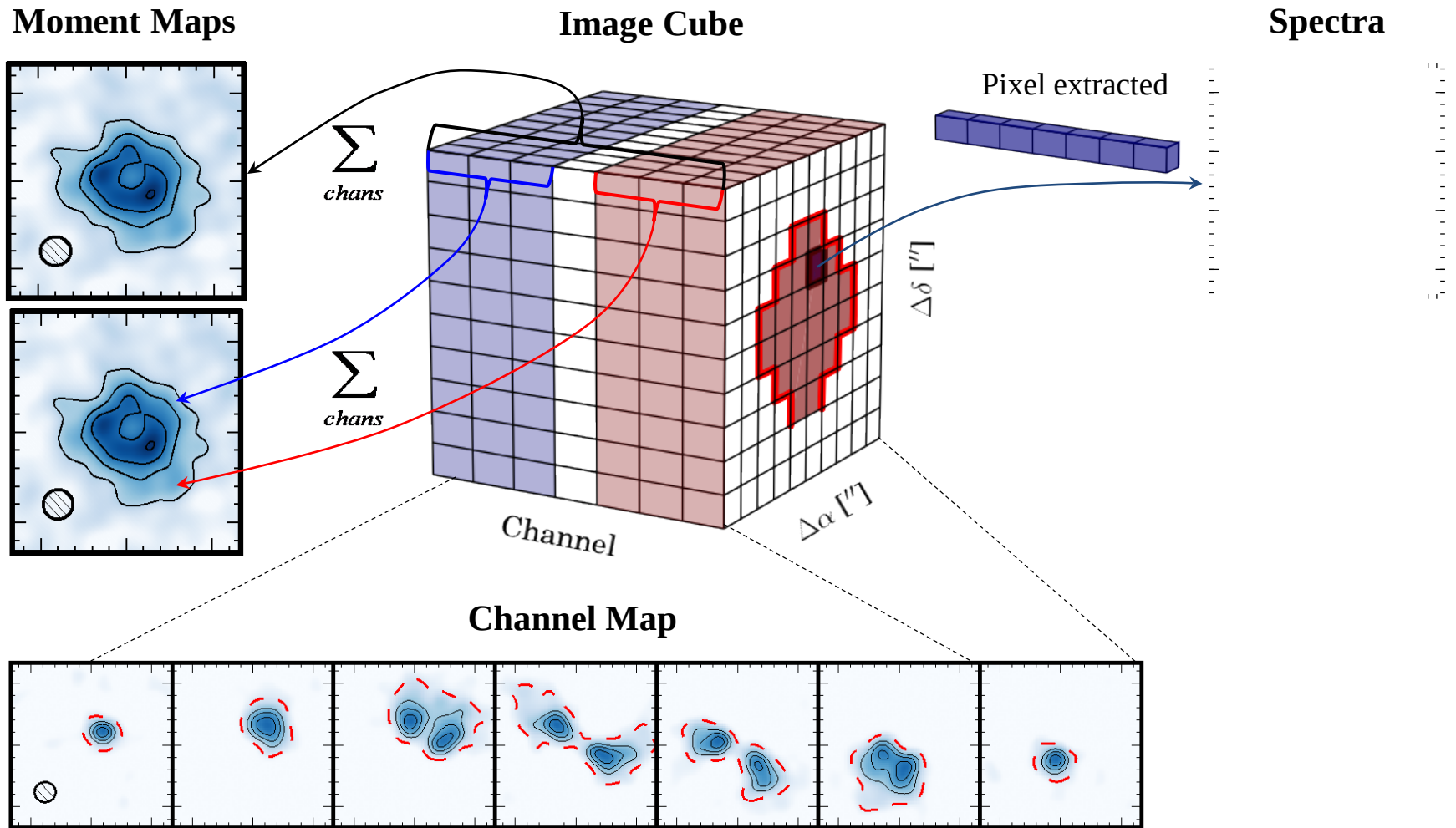
[Loomis + 2018]

Analyzing imaged observations



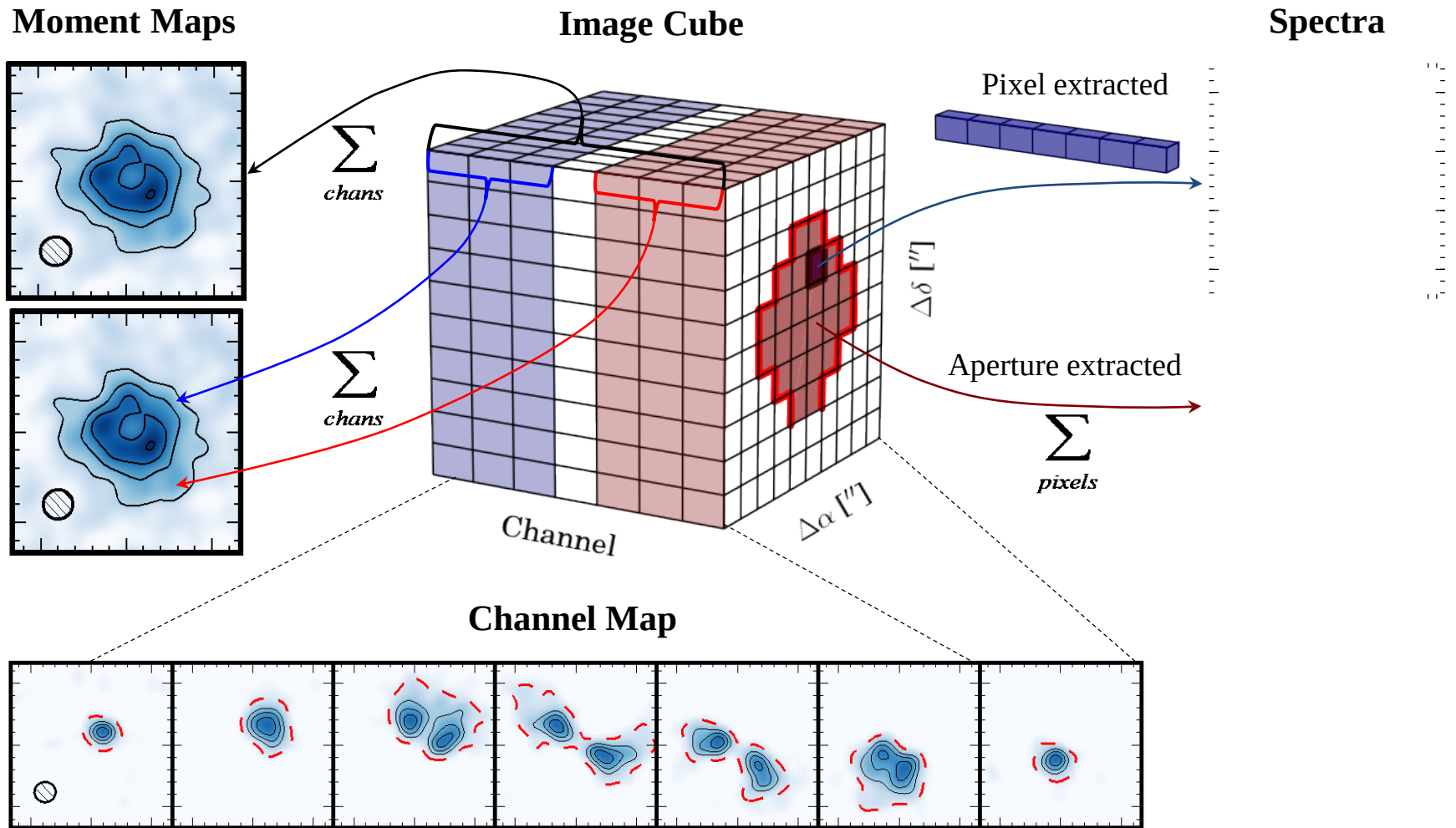
[Loomis + 2018]

Analyzing imaged observations



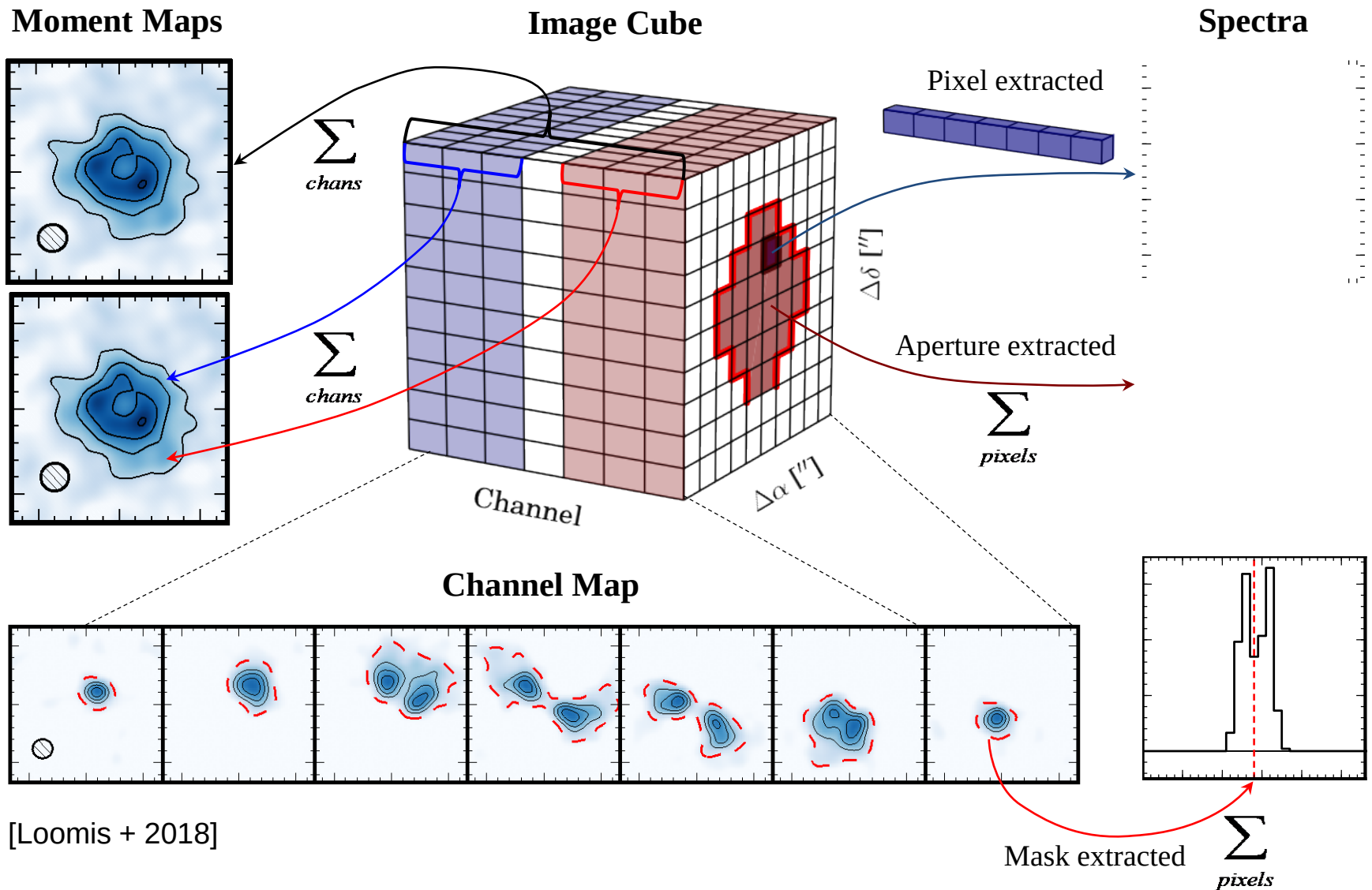
[Loomis + 2018]

Analyzing imaged observations

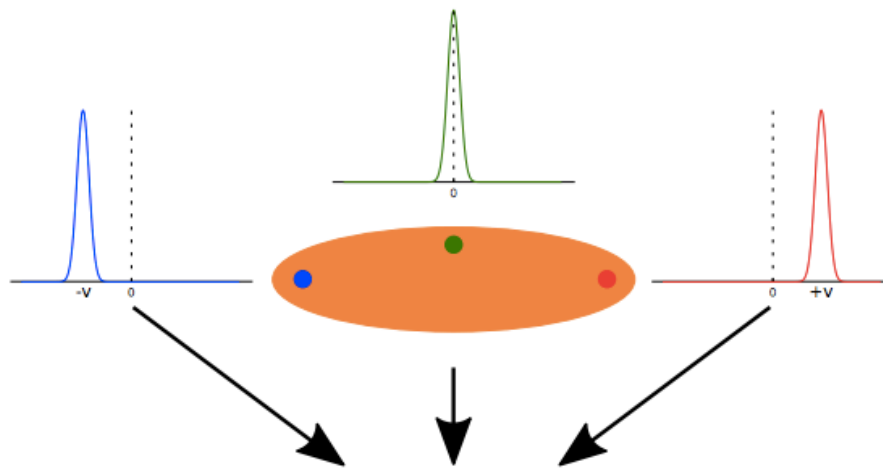


[Loomis + 2018]

Analyzing imaged observations

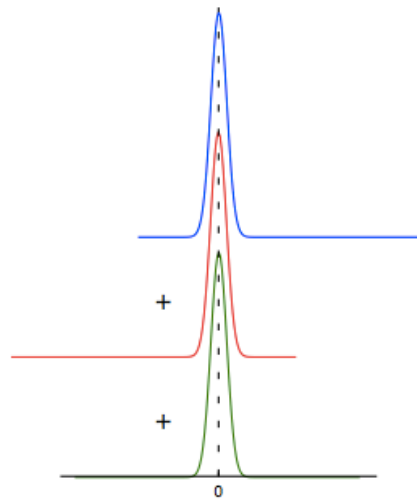


Spectral stacking



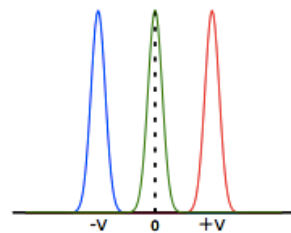
Stack

With alignment

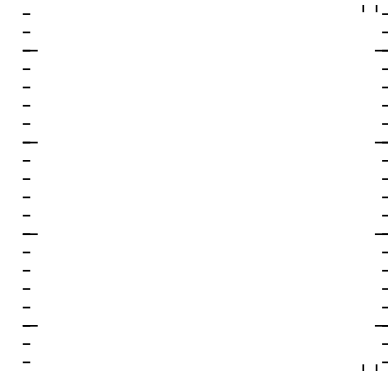
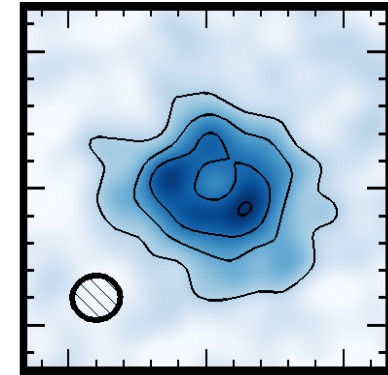


Peak intensity increases.

Without alignment



Peak intensity remains the same.

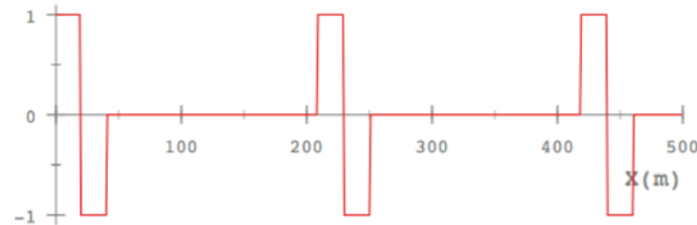


Matra + 2015
Marino + 2016
Yen + 2016

Matched filtering

Convolve known template signal with noisy data

Signal (used as filter/kernel)



Noisy signal



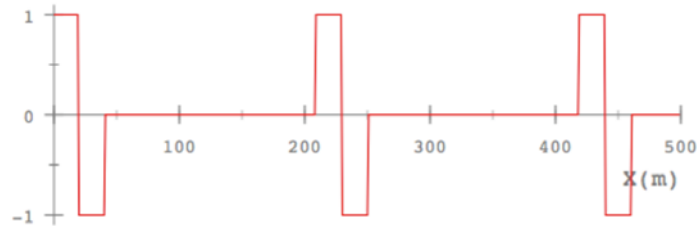
<http://www.grauonline.de/alexwww/ardumower/filter/filter.html>

https://lsc.ligo.org/tutorial_optimal/

Matched filtering

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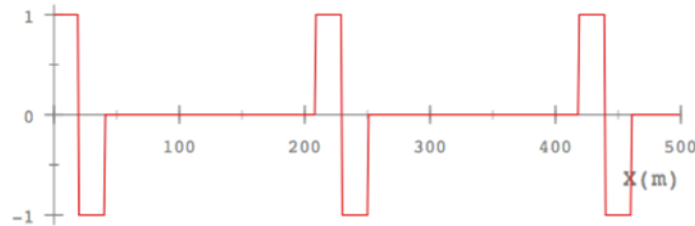
$$T_{i_0} = \sum_{i=i_0}^{i_0+N_s-1} x_i h_{i-i_0}; \quad i_0 = 0, 1, \dots, N - N_s$$

$$h = \frac{1}{s^H R_v^{-1} s} R_v^{-1} s$$

Matched filtering

Convolve known template signal with noisy data

Signal (used as filter/kernel)



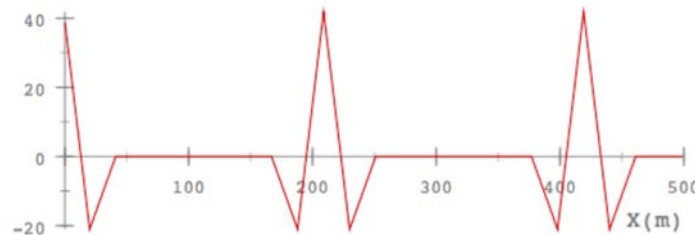
Noisy signal



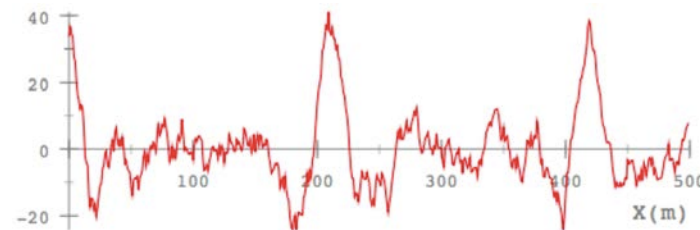
$$T_{i_0} = \sum_{i=i_0}^{i_0+N_s-1} x_i h_{i-i_0}; \quad i_0 = 0, 1, \dots, N - N_s$$

Filter response has highest recoverable SNR

Autocorrelation of signal



Filter response



<http://www.grauonline.de/alexwww/ardumower/filter/filter.html>

https://lsc.ligo.org/tutorial_optimal/

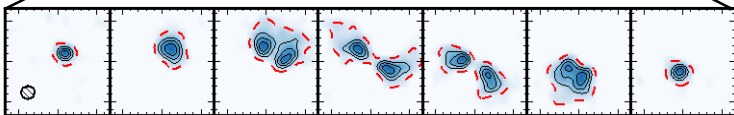
Matched filtering interferometric data

KERNEL (f)

n_k

n_{uv}

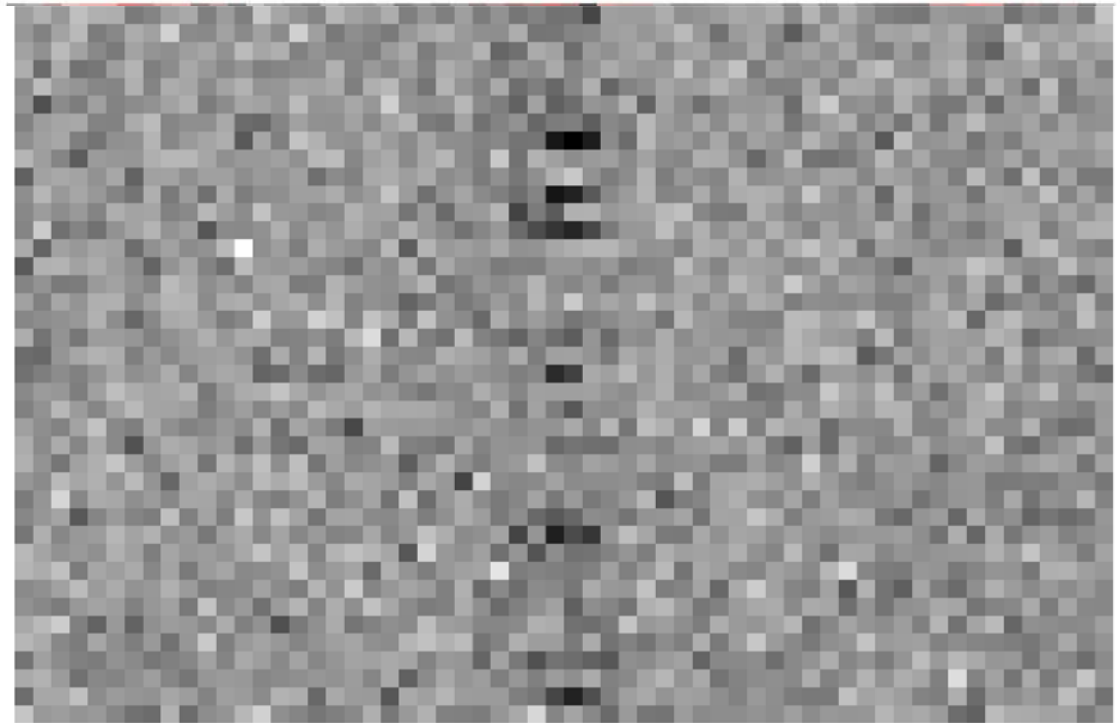
FFT
↑



DATA (V)

n_c

n_{uv}



Matched filtering interferometric data

KERNEL (f)

n_k

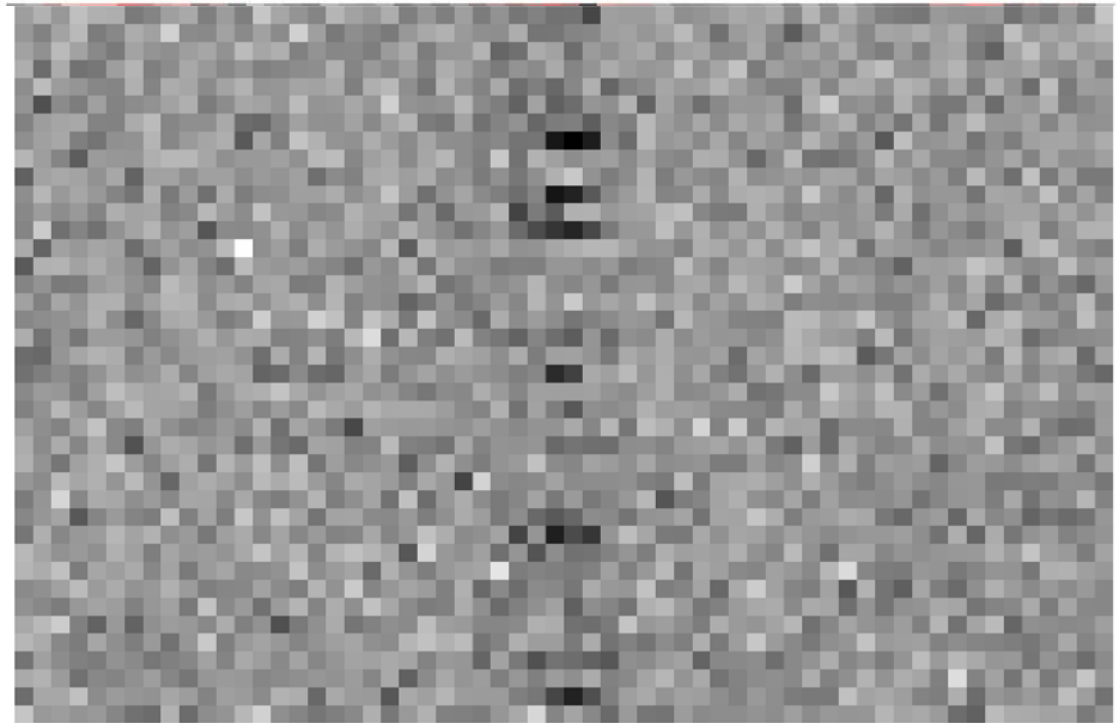
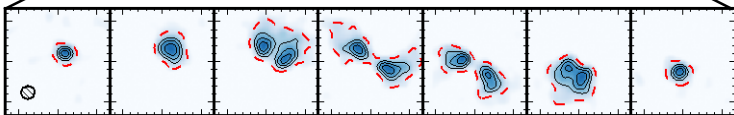
n_{uv}

*

DATA (V)

n_c

FFT



Matched filtering interferometric data

KERNEL (f)

n_k

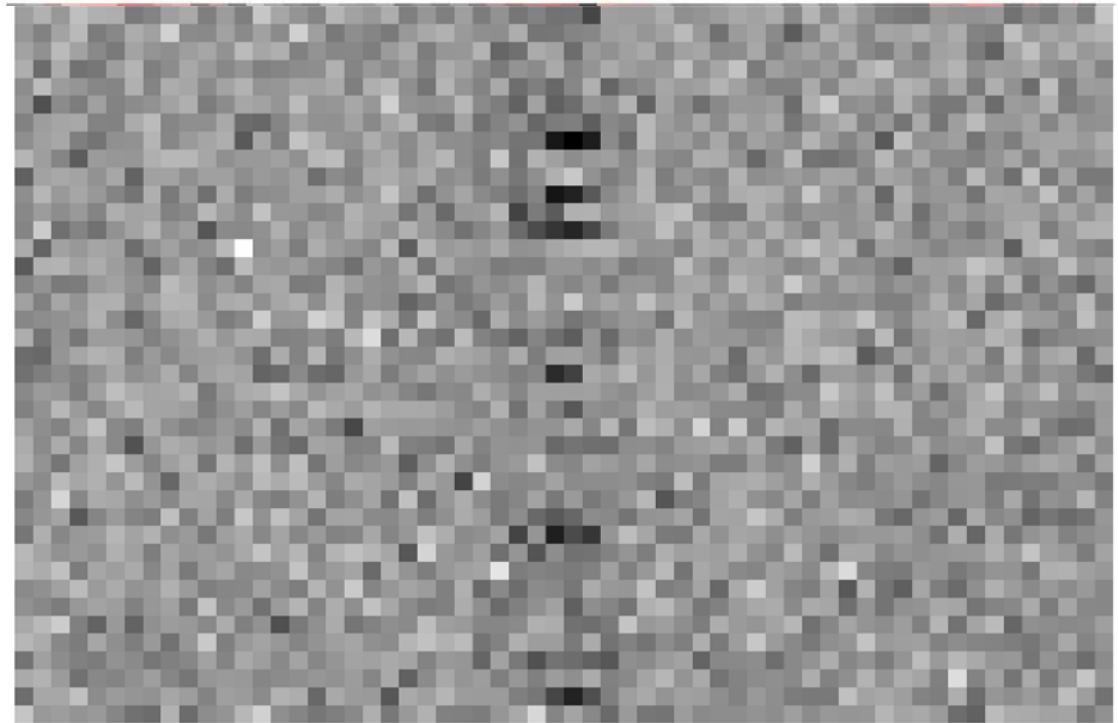
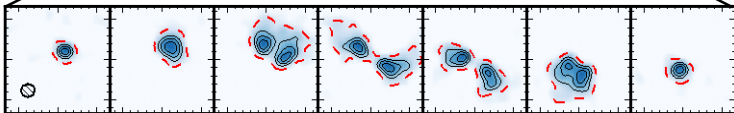
n_{uv}

*

DATA (V)

n_c

FFT



$$T_{i_0} = \text{Re} \left[\sqrt{2} \sum_{i=i_0}^{i_0+n_k-1} \sum_{j=0}^{n_{uv}} V_{i,j} h_{i-i_0,j} \right]; \quad i_0 \in [0, n_c - n_k],$$

IMPULSE RESPONSE SPECTRUM (T)

Matched filtering interferometric data

KERNEL (f)

n_k

n_{uv}

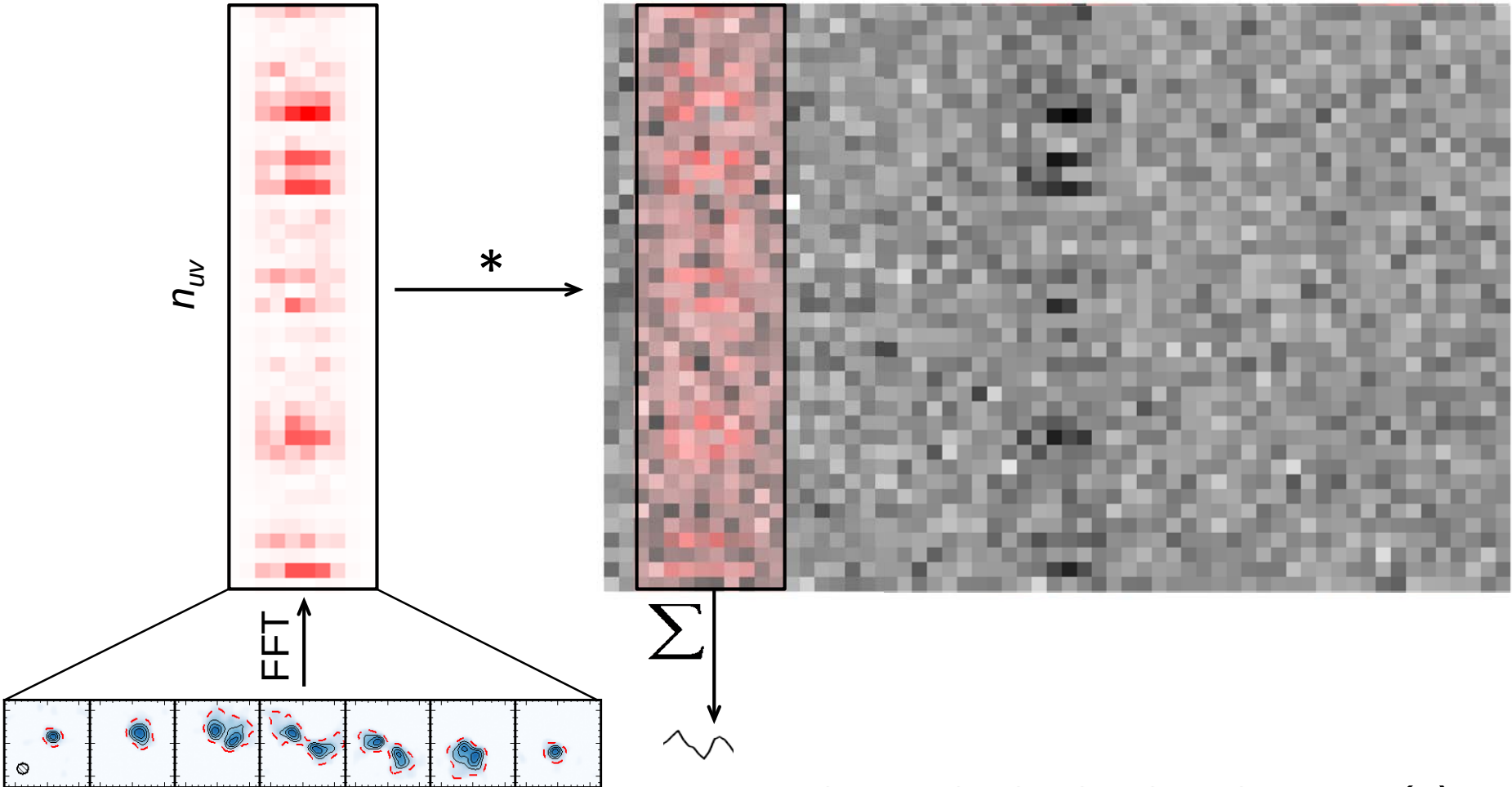
*

DATA (V)

n_c

Σ

IMPULSE RESPONSE SPECTRUM (T)



Matched filtering interferometric data

KERNEL (f)

n_k

n_{uv}

*

DATA (V)

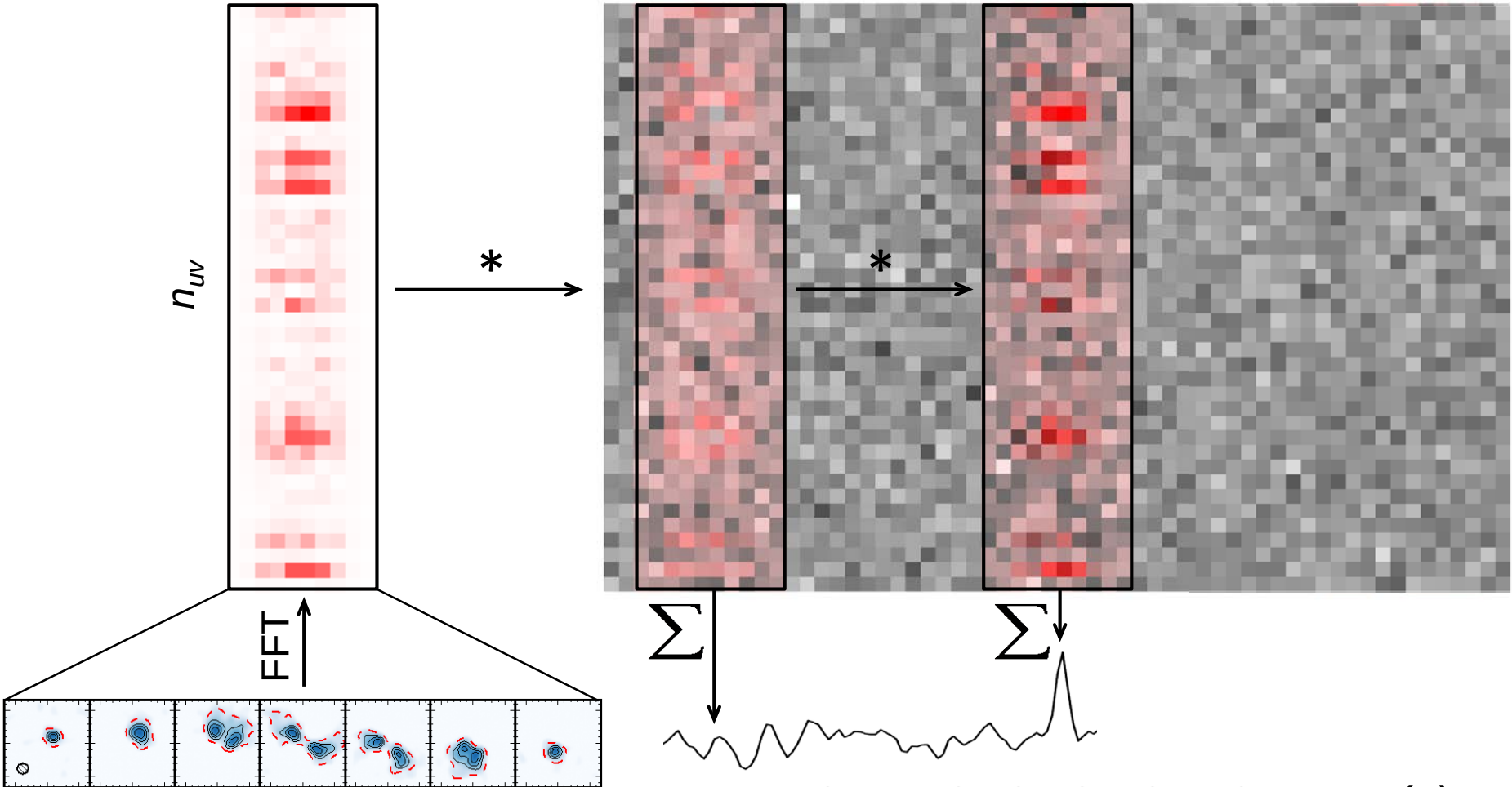
n_c

*

Σ

Σ

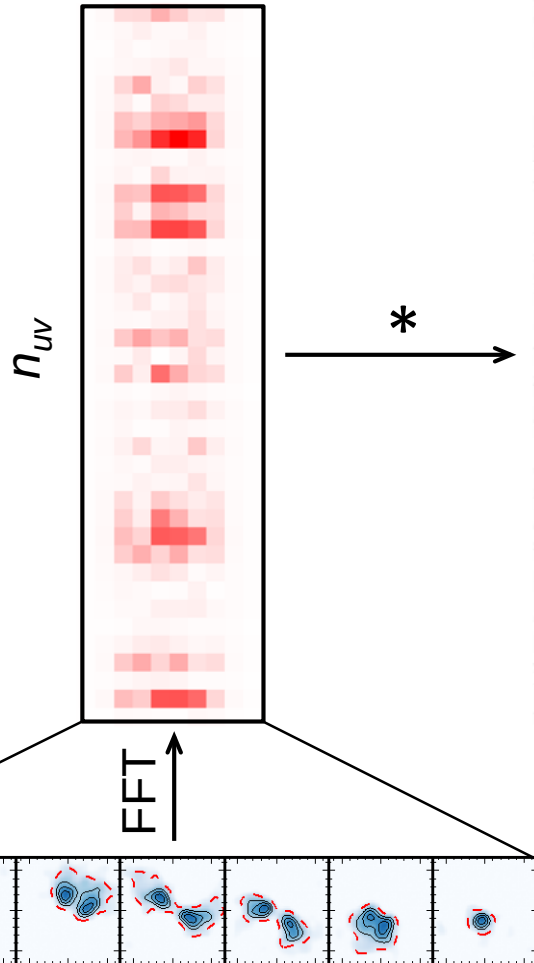
IMPULSE RESPONSE SPECTRUM (T)



Matched filtering interferometric data

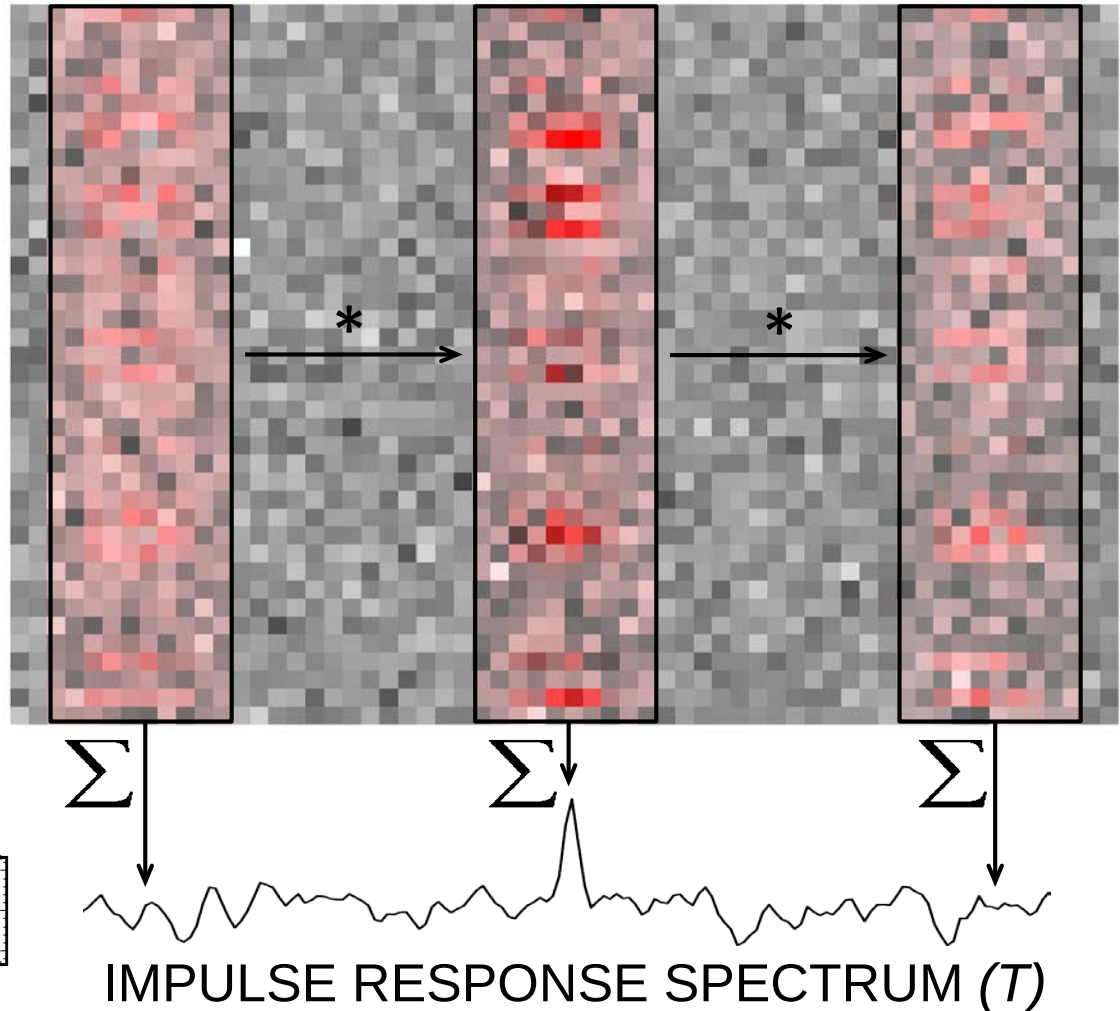
KERNEL (f)

n_k

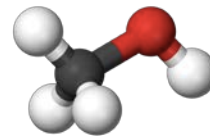


DATA (V)

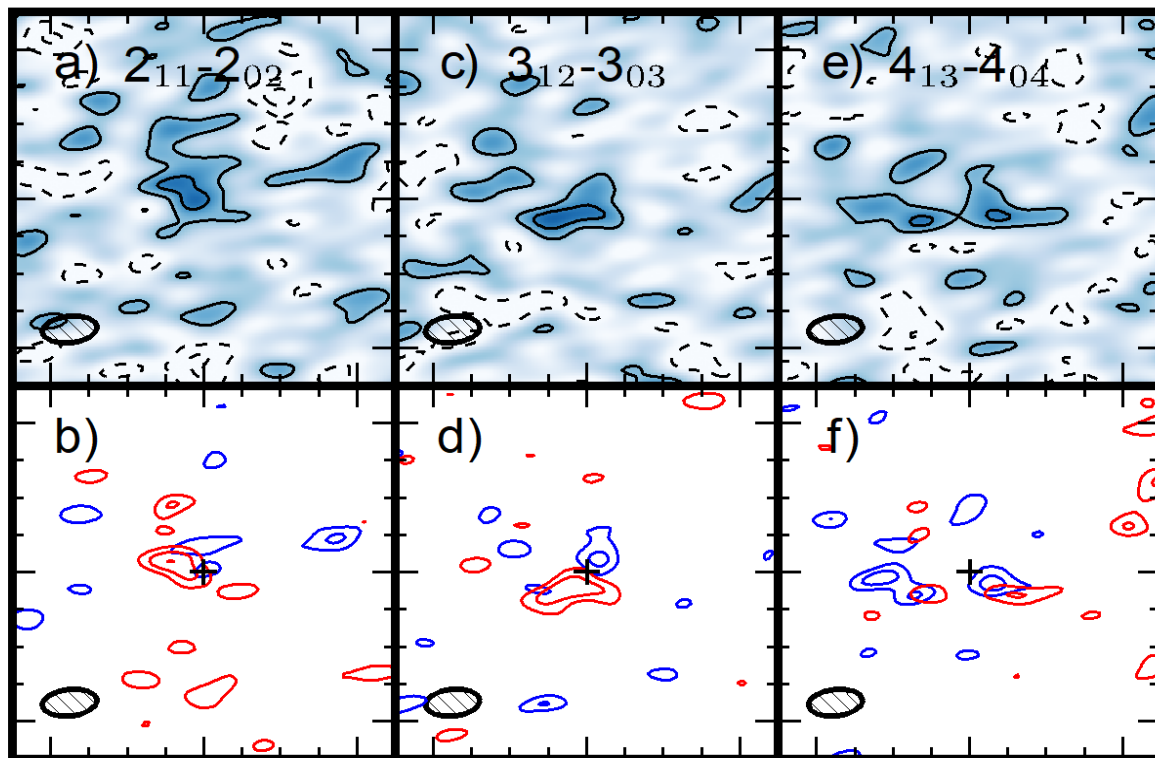
n_c



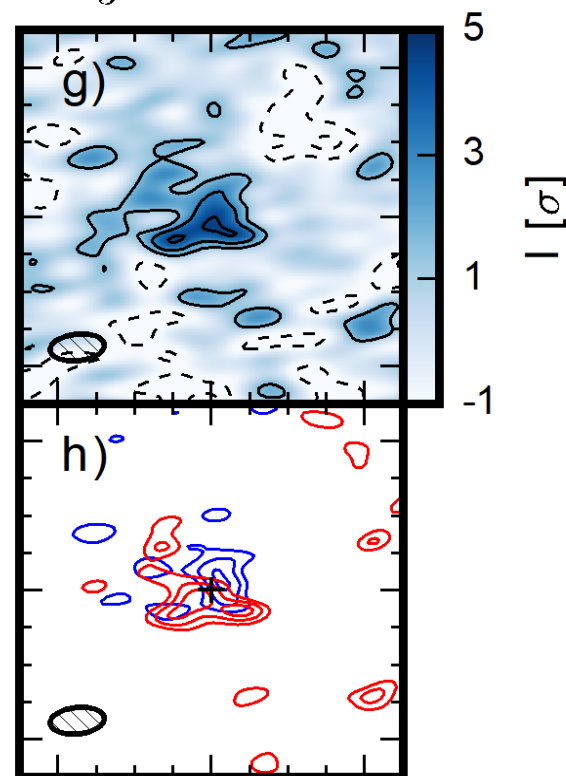
Test case #1 – CH₃OH in TW Hya



CH₃OH Individual Lines

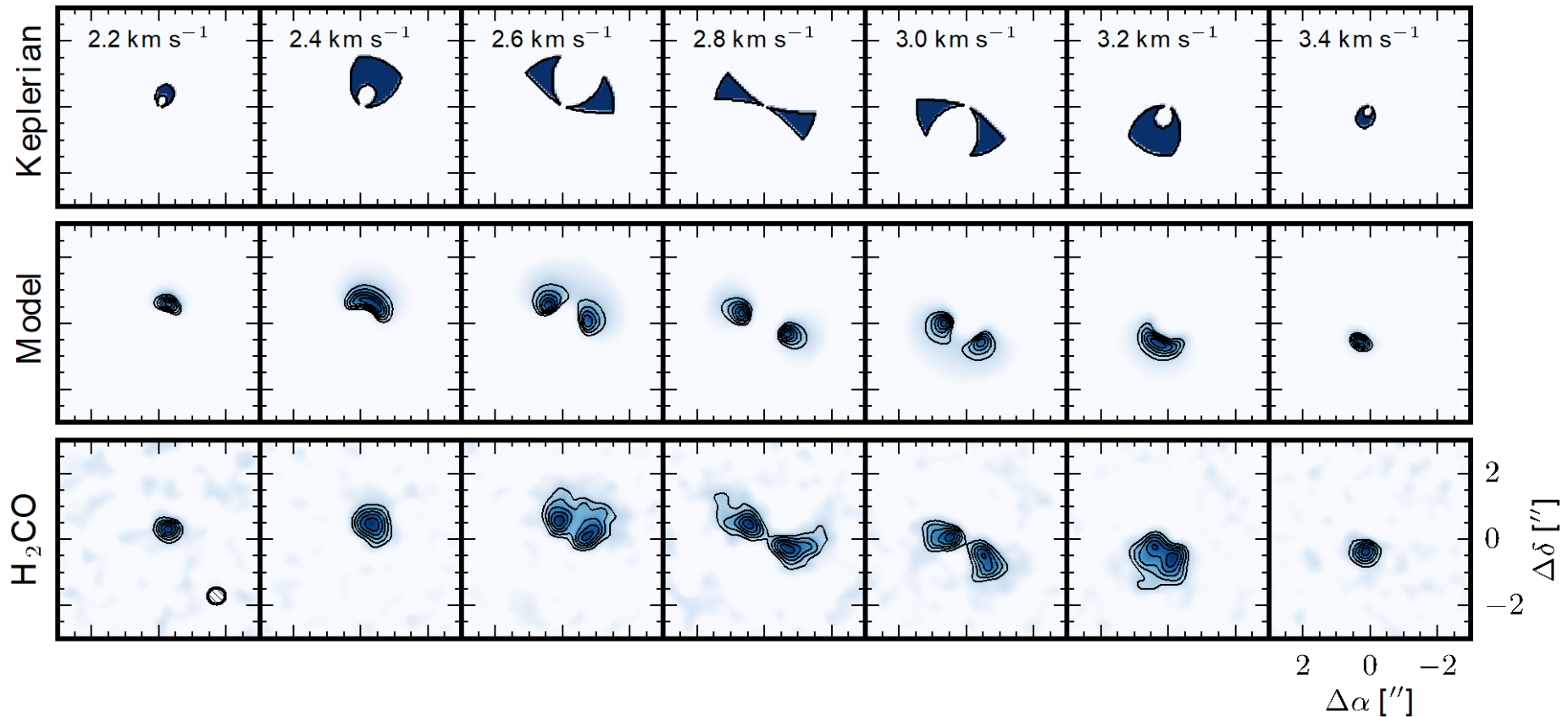
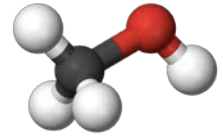


CH₃OH Stacked



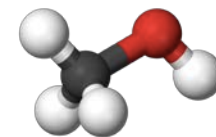
[Walsh, Loomis, Öberg + 2016]

Test case #1 – CH₃OH in TW Hya

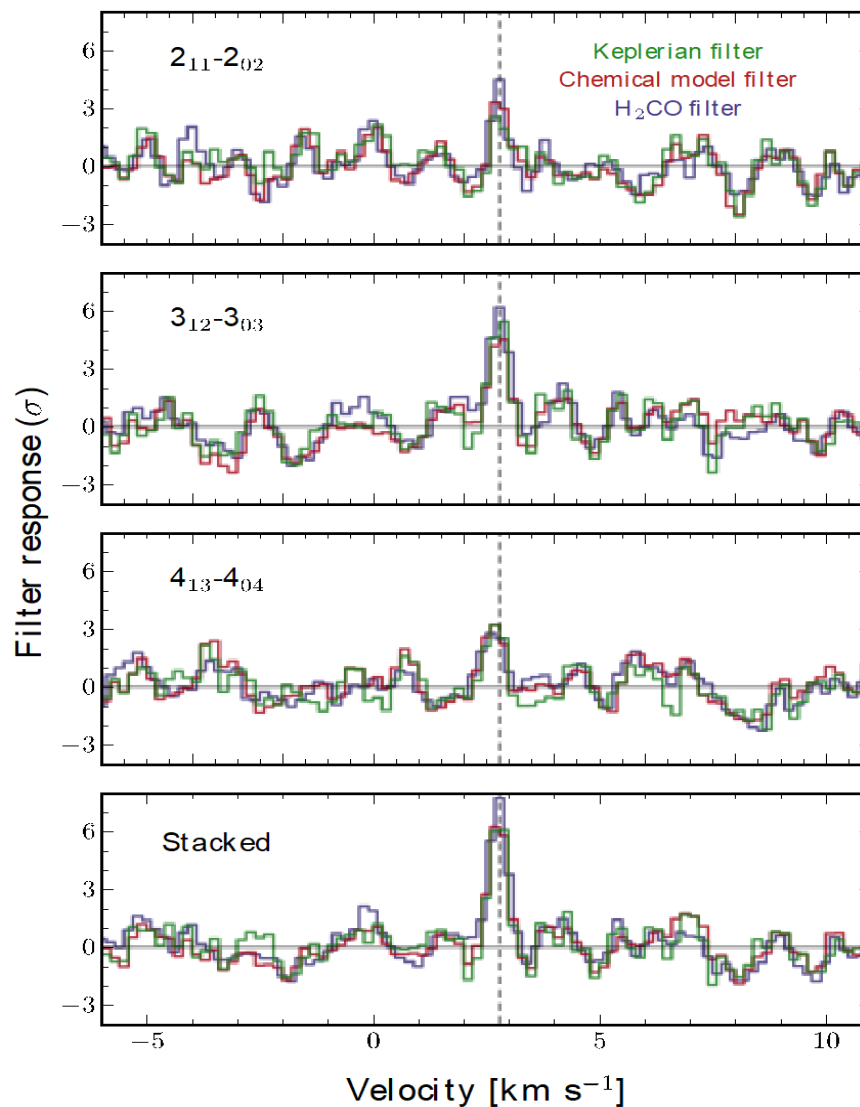


[Loomis + 2018]

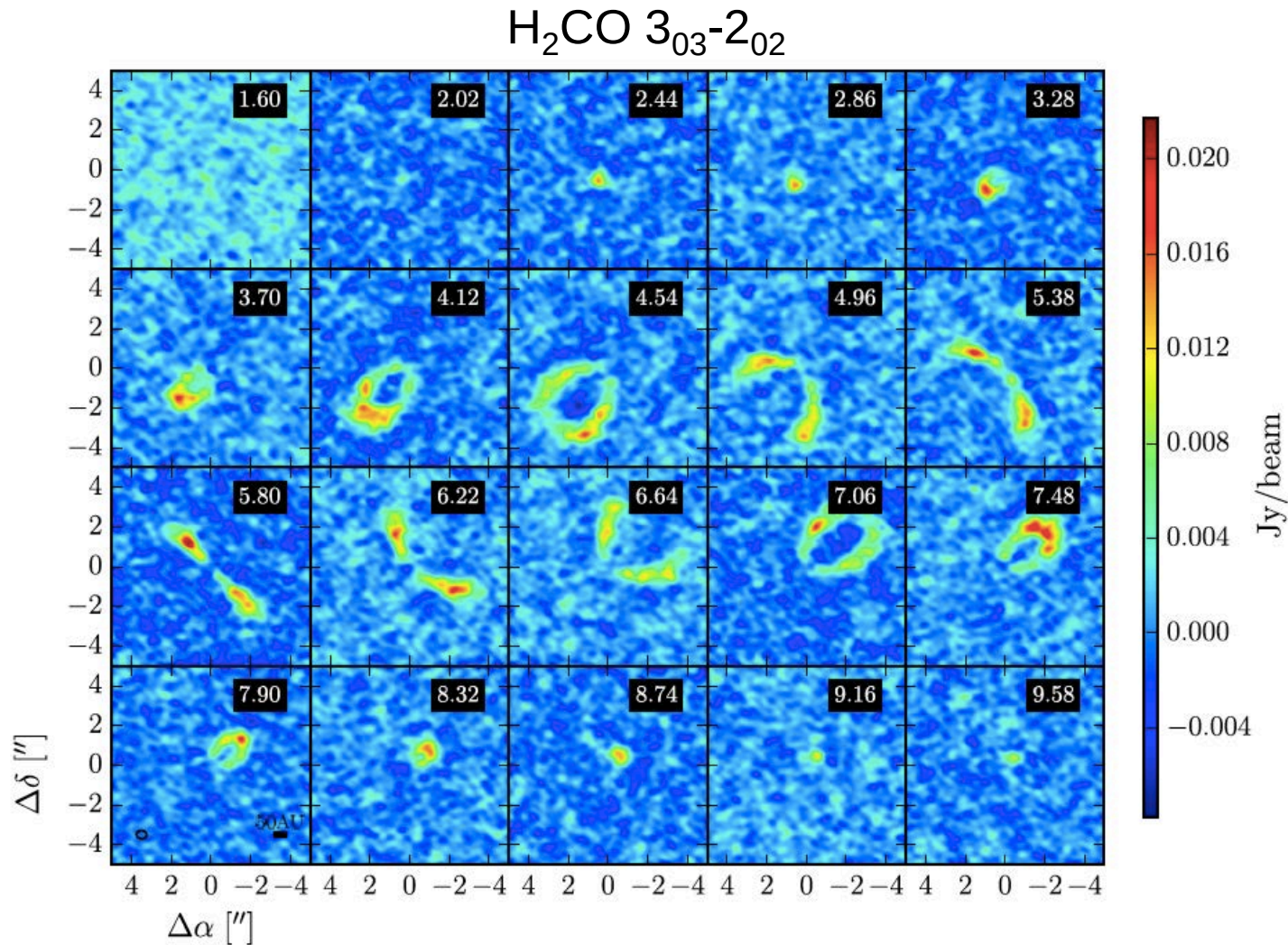
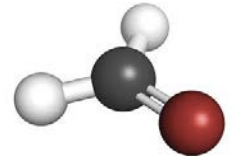
Test case #1 – CH₃OH in TW Hya



- Individual lines are now detected
- SNR significantly enhanced – 7.8σ after matched filtering vs 5.1σ before (53% improvement)
- 53% SNR boost is equivalent to a factor of 2.3 in observing time

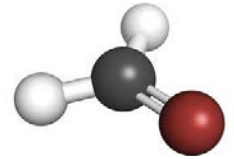


Test case #2 – H₂CO in HD 163296

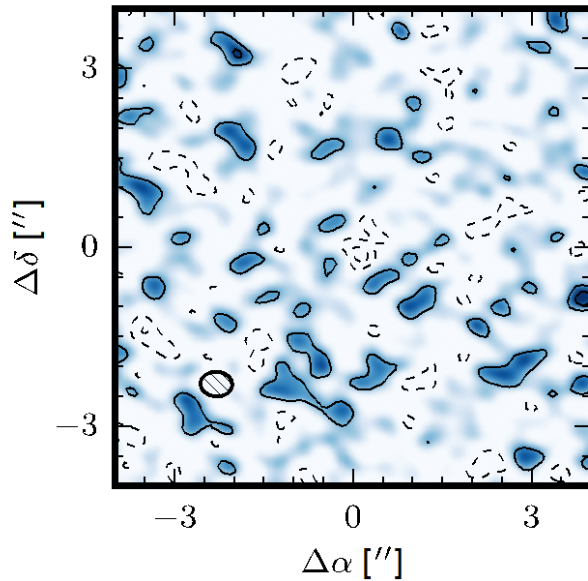


Carney + 2017

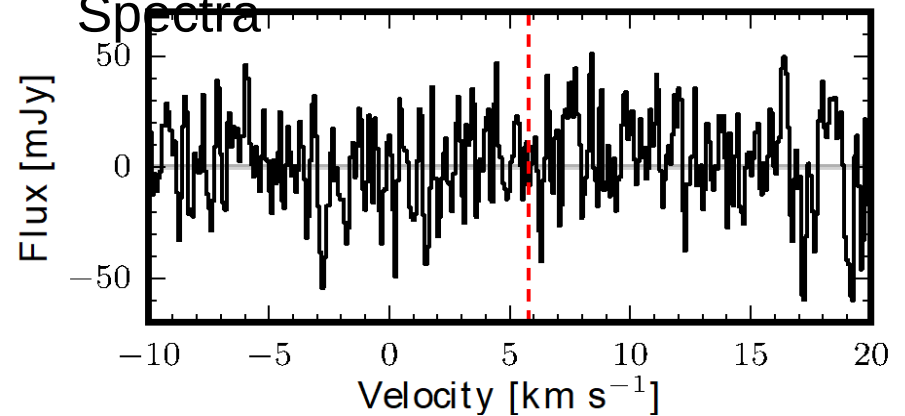
Test case #2 – H₂CO in HD 163296



$3_{22}-2_{21} + 3_{21}-2_{20}$ Moment-0

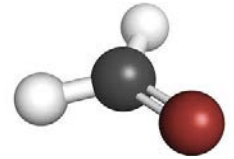


H₂CO $3_{22}-2_{21} + 3_{21}-2_{20}$ Stacked Spectra

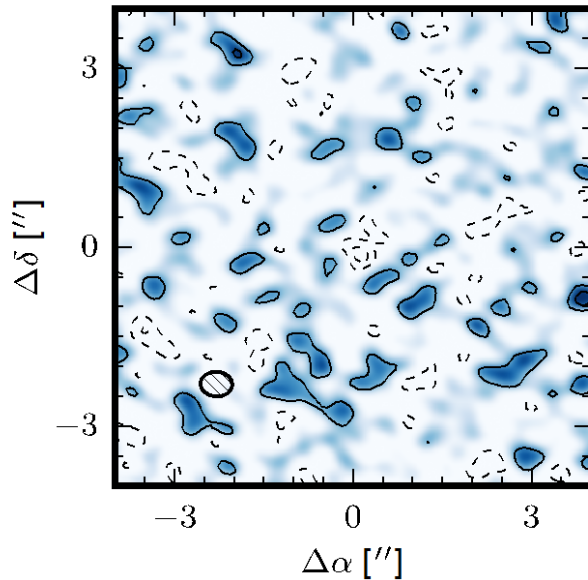


Carney + 2017

Test case #2 – H₂CO in HD 163296



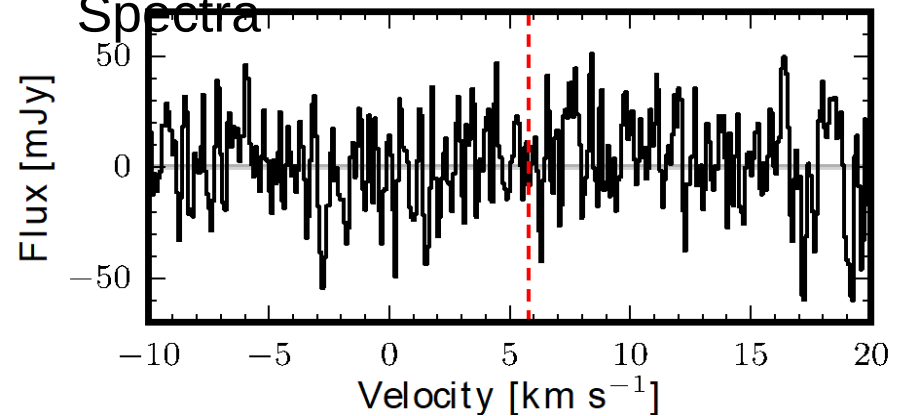
$3_{22}-2_{21} + 3_{21}-2_{20}$ Moment-0



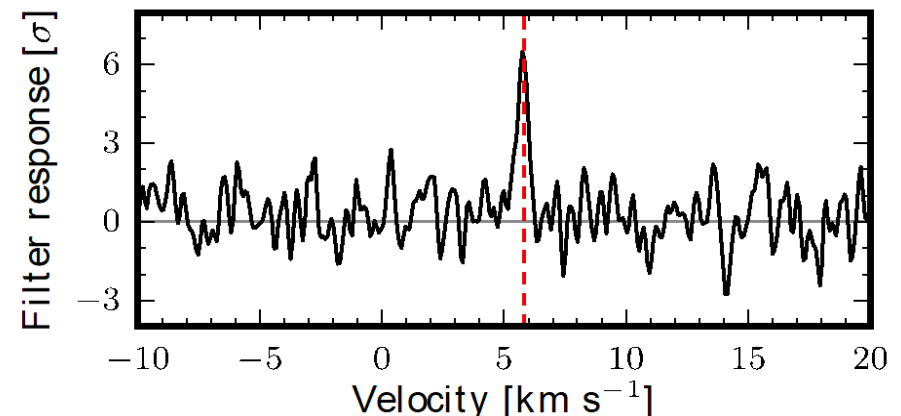
>500% SNR boost!

Carney + 2017

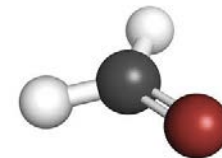
H₂CO $3_{22}-2_{21} + 3_{21}-2_{20}$ Stacked Spectra



Matched filter

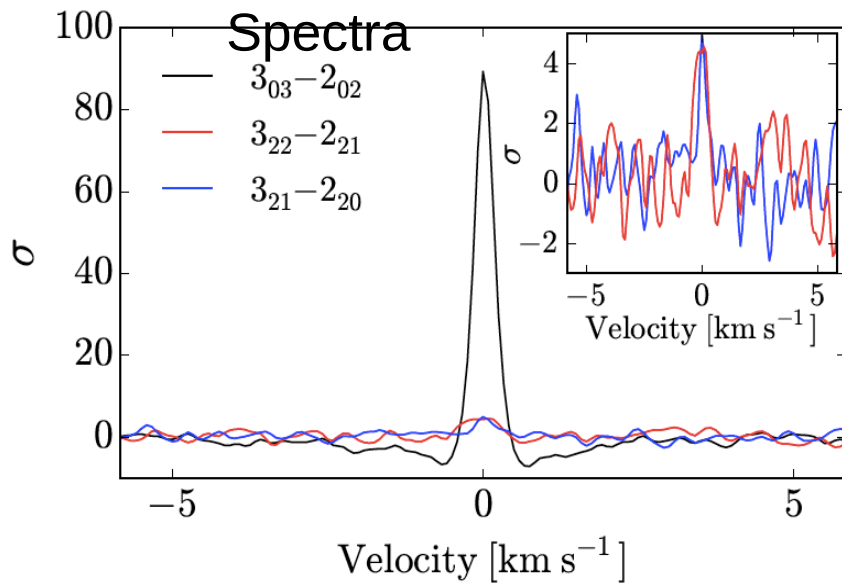


Test case #2 – H₂CO in HD 163296



H₂CO Response

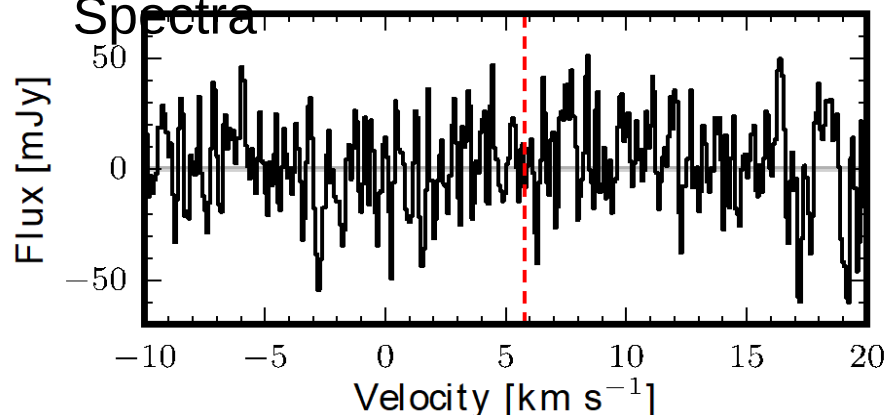
Spectra



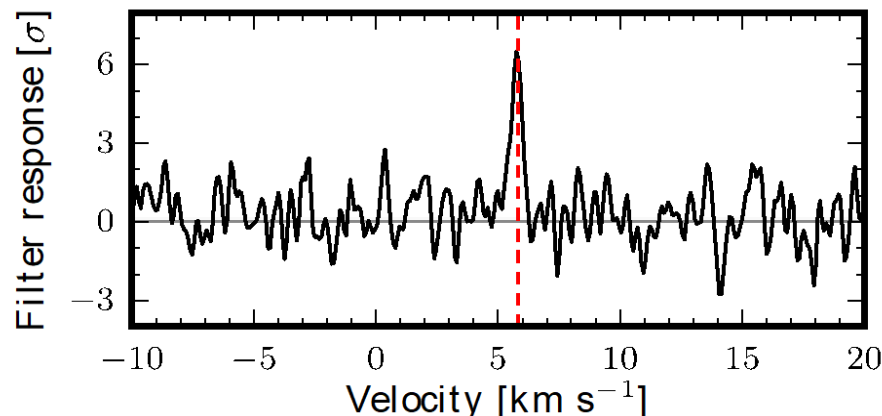
>500% SNR boost!

Carney + 2017

H₂CO $3_{22}-2_{21} + 3_{21}-2_{20}$ Stacked Spectra



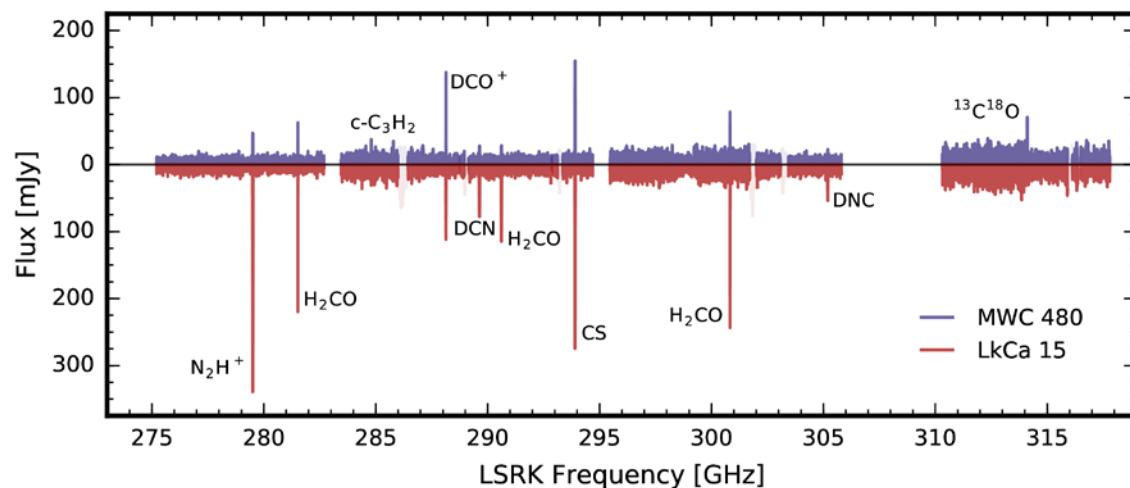
Matched filter



ALMA Band 7 Disk Spectral Survey

Aperture-extraction

- ~40-50 hrs to image, clean, and extract spectra
- 10 detected species

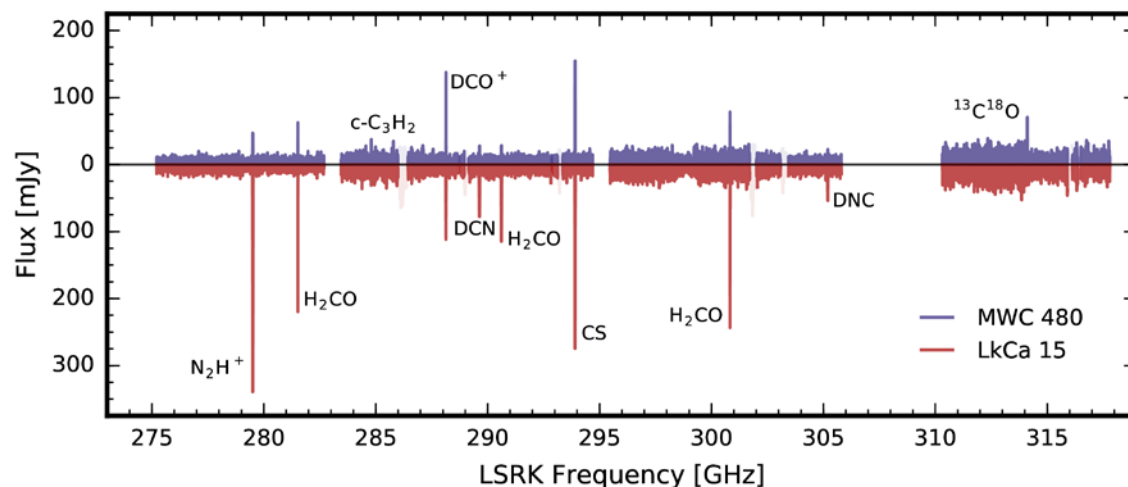


[Loomis + in prep]

ALMA Band 7 Disk Spectral Survey

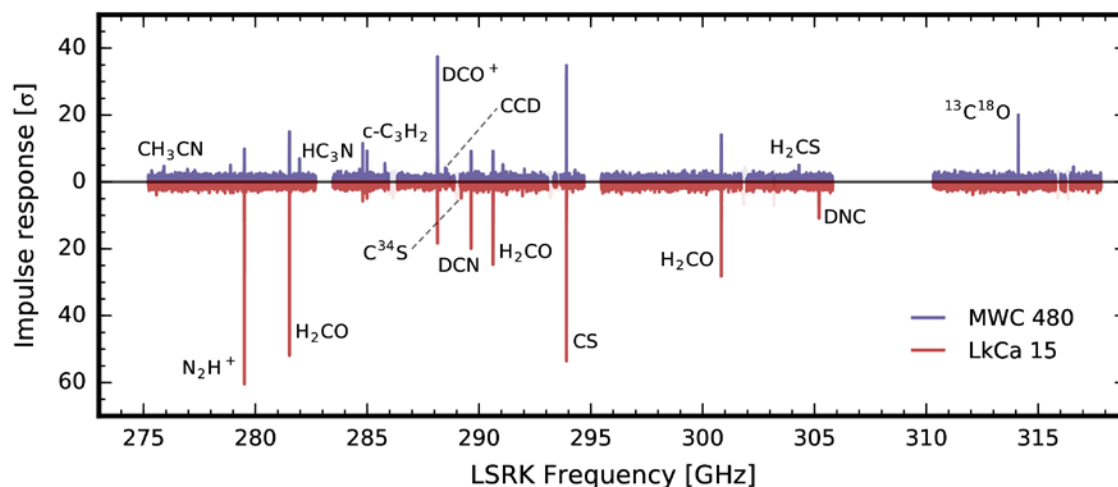
Aperture-extraction

- ~40-50 hrs to image, clean, and extract spectra
- 10 detected species



Matched filtering

- ~30 min to filter entire survey
- SNR 2-3x higher
- 16 detected species
- 5 new disk species: ^{13}CS , C^{34}S , DNC , CCD , H_2CS



[Loomis + in prep]

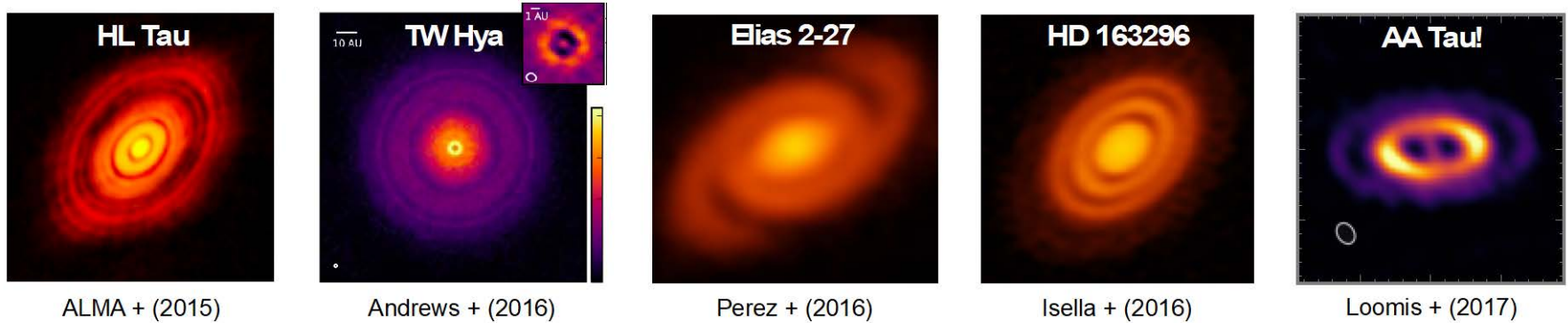
Summary

- Matched filtering can boost SNR of weak spectral lines by >500%
- Useful for fast *uv* plane analysis of large bandwidth datasets
 - No prior imaging necessary!
- Not limited to disks – method is general
 - Ideal for resolved sources with PV structure

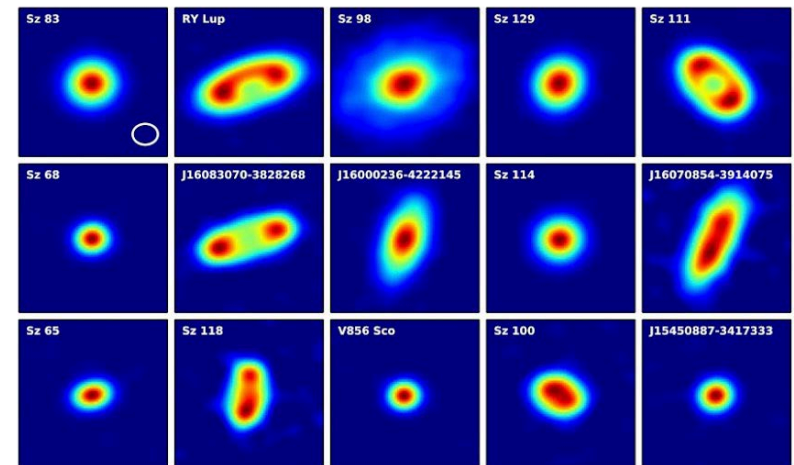
Outline

- Matched filtering for improved weak spectral line detection
- **Generalized Briggs weighting for improved image fidelity**

Motivation



- Many resolved sources now showing sub-structure
- SNR limitations may prevent imaging this sub-structure in weaker sources

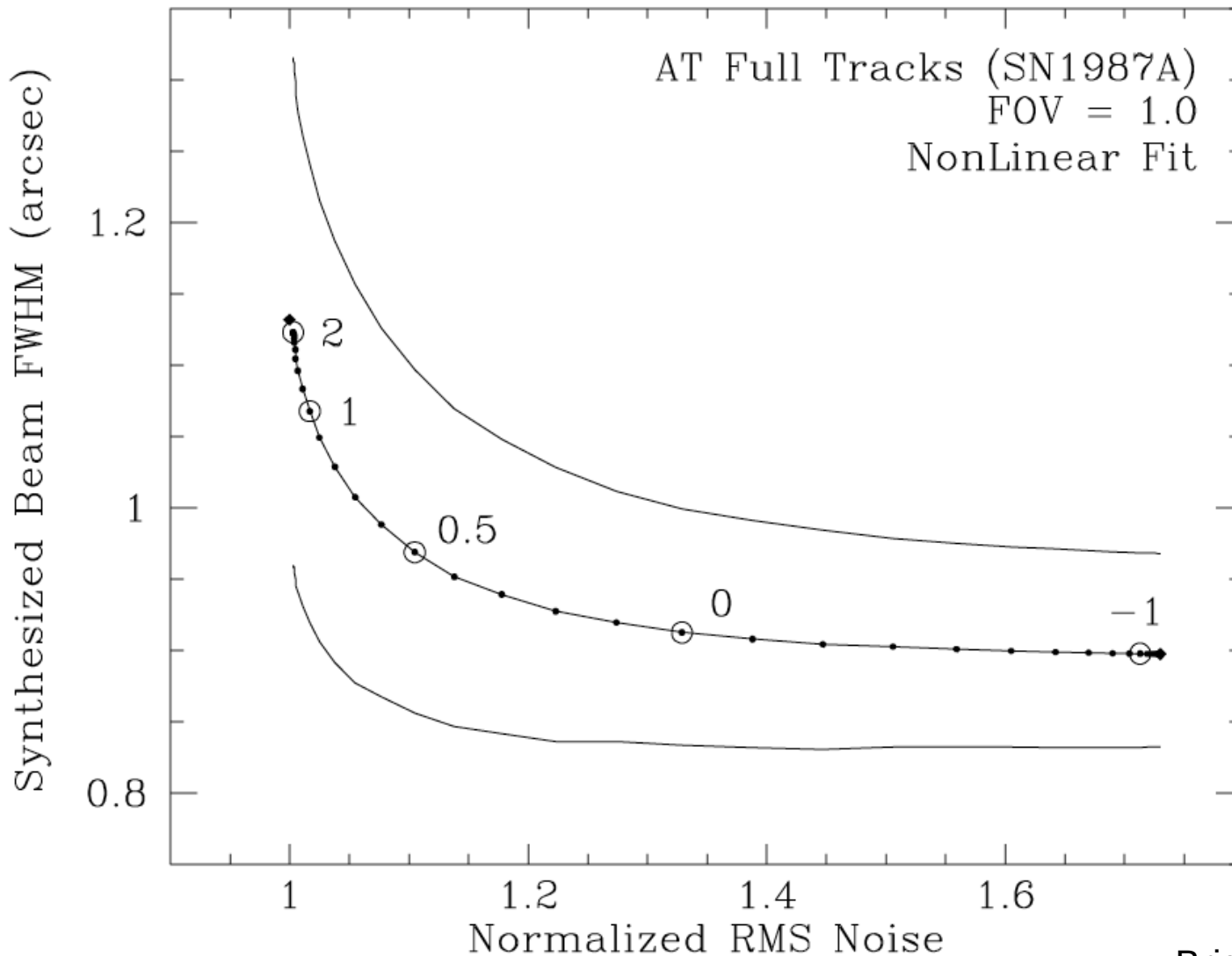


Ansdell + 2016

Types of weighting

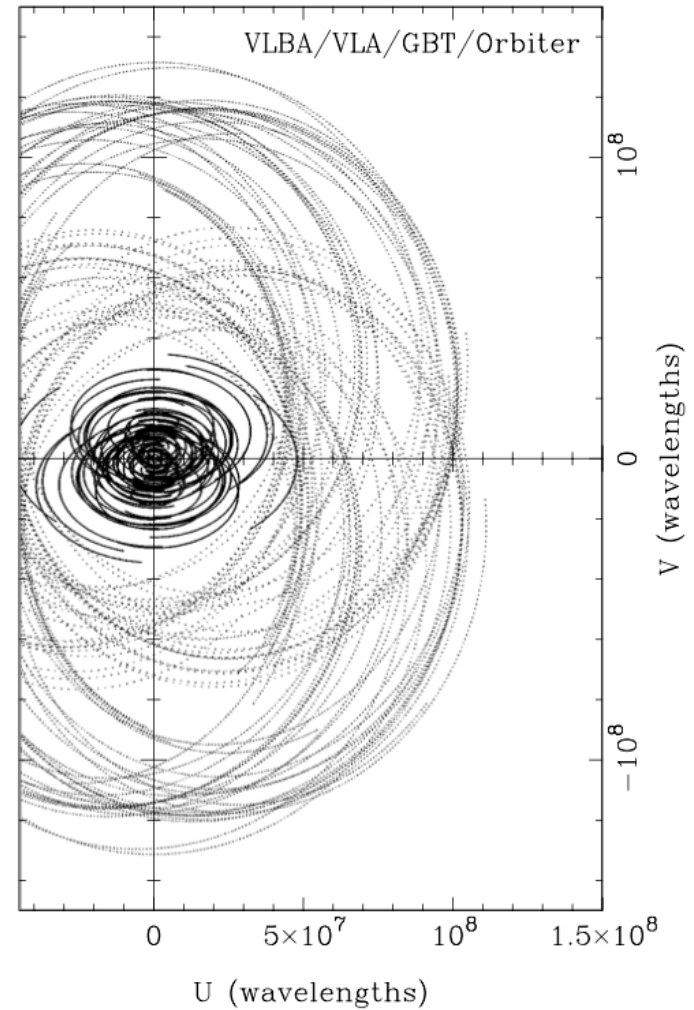
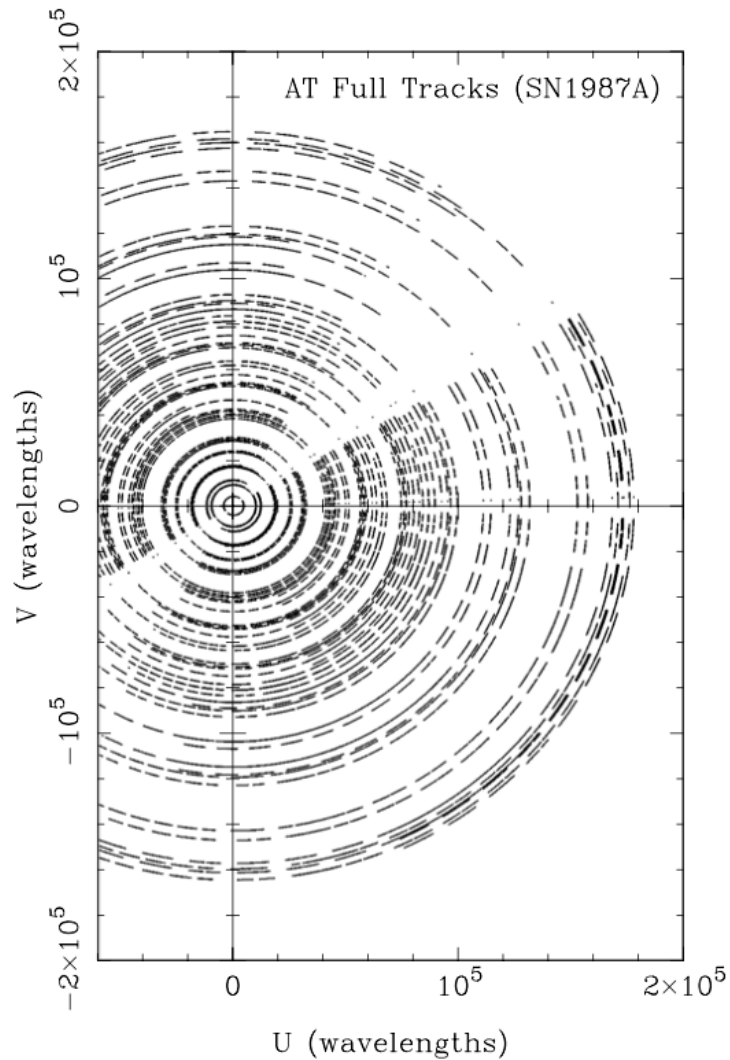
- Natural – lowest rms in dirty image
- Uniform – lowest sidelobes, higher resolution
- Robust – tunable between natural and uniform
 - Retains benefits of both
- Tapering – generally Gaussian taper
 - Sacrifices resolution for increased sensitivity to extended structure

Robust weighting



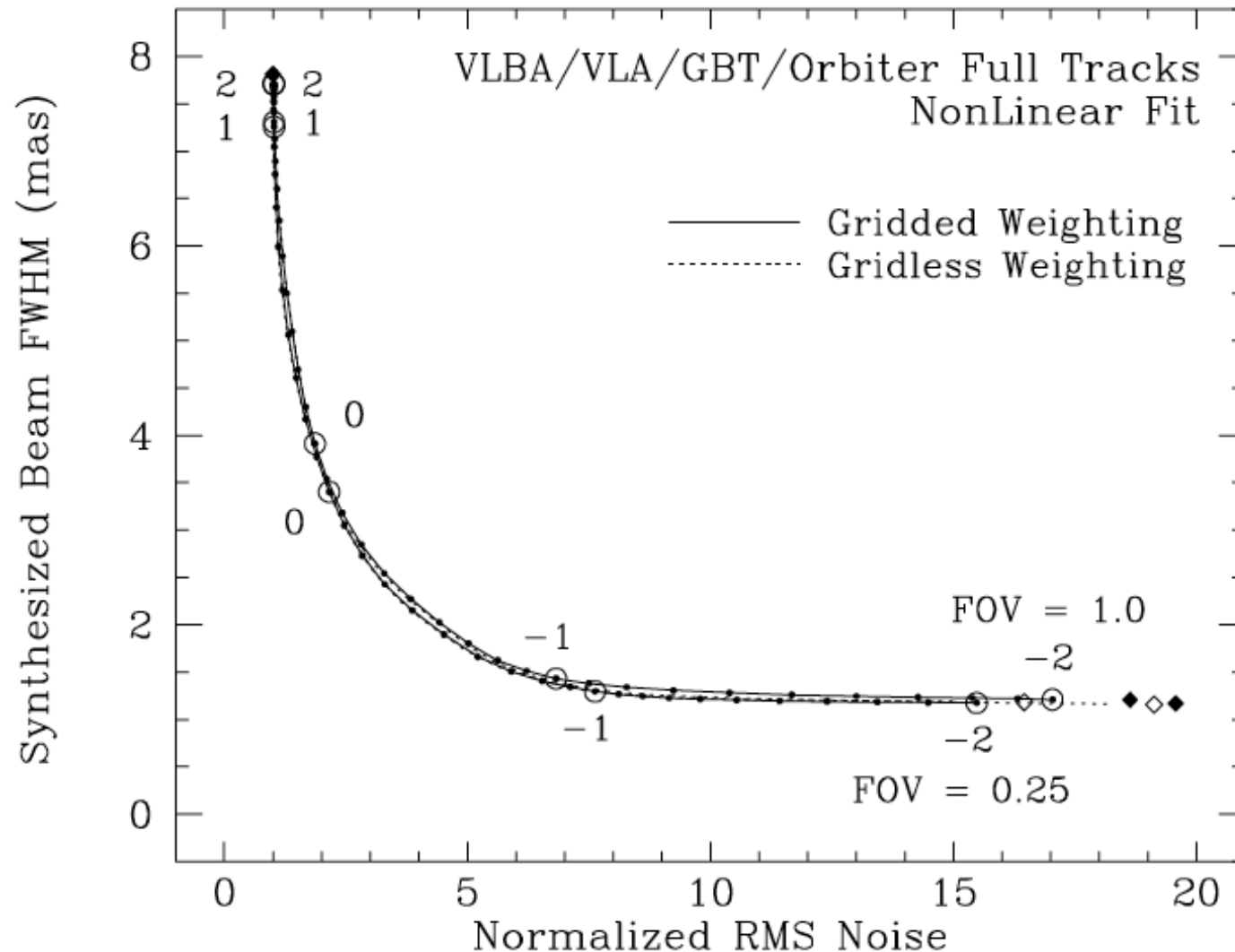
Briggs 1995

UV coverage and array balance



Briggs 1995

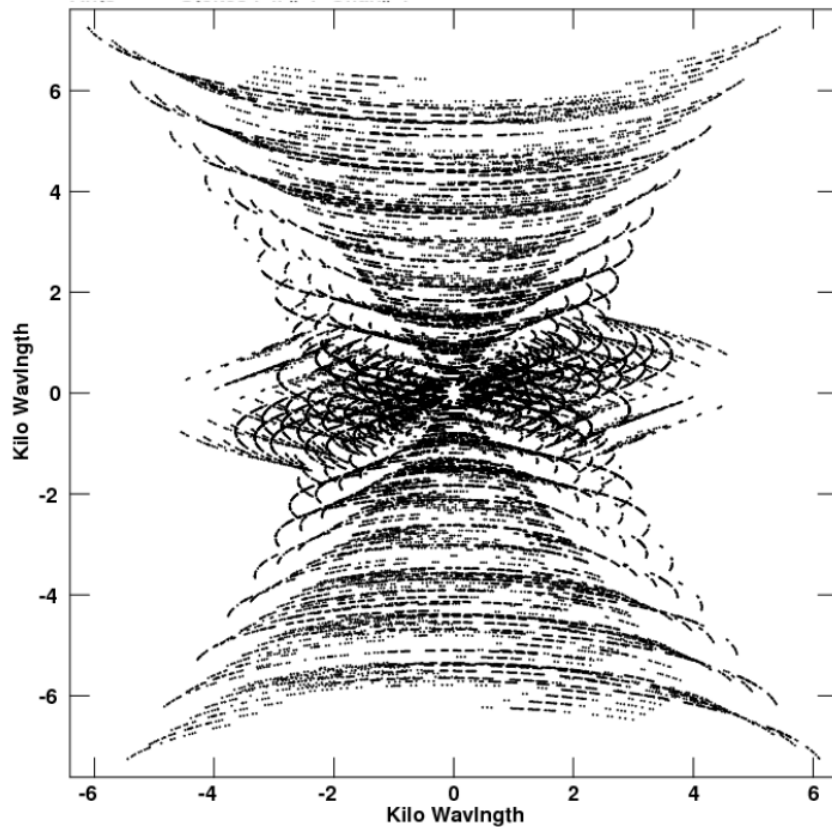
Robust weighting



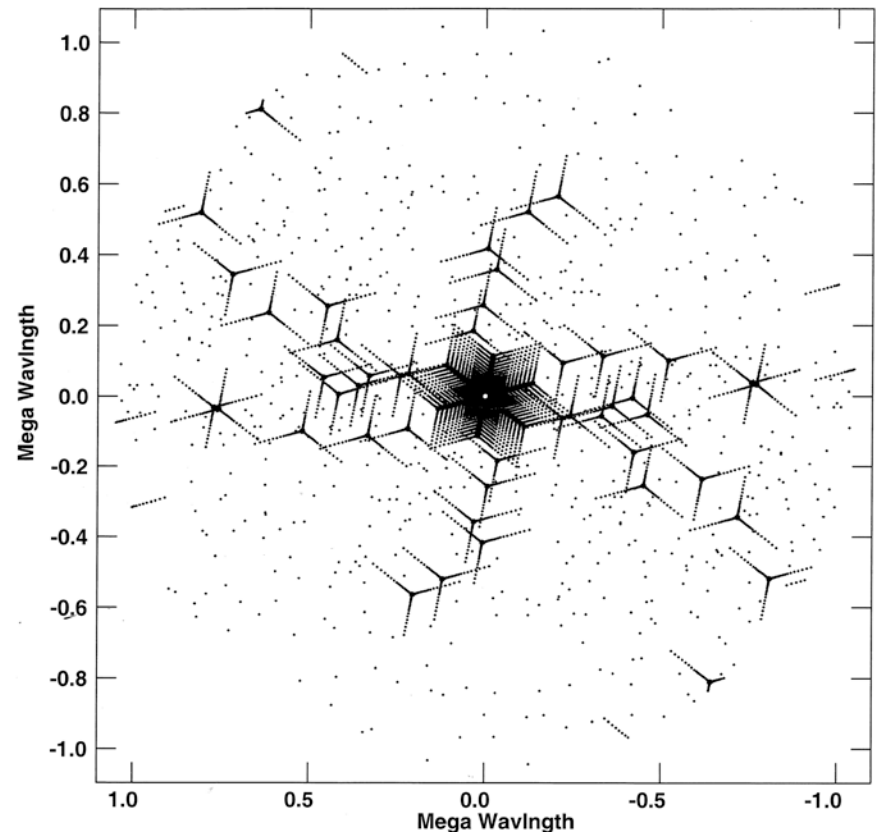
Briggs 1995

UV coverage and array balance

ALMA



ngVLA



Eric Murphy's bulletin board

Why does robust weighting work?

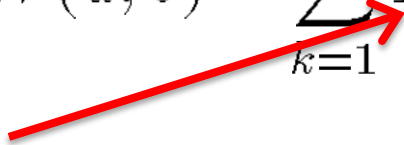
Definitions

Weights:
$$W(u, v) = \sum_{k=1}^{2L} T_k D_k w_k \delta(u - u_k, v - v_k)$$

Definitions

Weights: $W(u, v) = \sum_{k=1}^{2L} T_k D_k w_k \delta(u - u_k, v - v_k)$

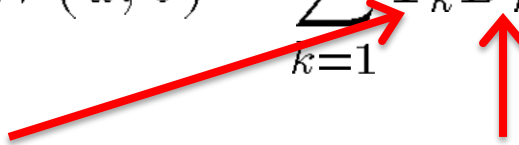
Taper weights



Definitions

Weights:
$$W(u, v) = \sum_{k=1}^{2L} T_k D_k w_k \delta(u - u_k, v - v_k)$$

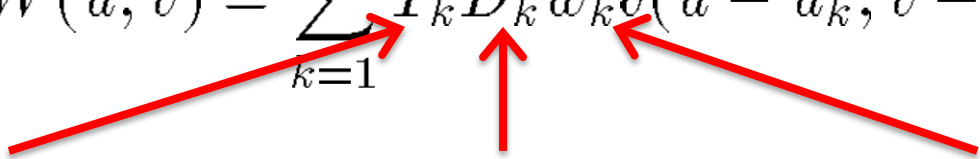
Taper weights Density weights



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RMS thermal noise:
$$\Delta I^D \propto \sqrt{\sum_{k=1}^L T_k^2 D_k^2 w_k}$$

Briggs 1995

Natural weighting

- Minimize $(\Delta I^D)^2$ using Lagrangian multiplier:

$$\frac{\partial}{\partial D_k} \left[\left(\frac{\Delta I^D}{2C} \right)^2 + \lambda \left(\sum T_k D_k w_k - W \right) \right] = 0$$

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$$T_k D_k w_k \propto 1/\sigma_k^2$$

- Thermal noise is lowest if T_k and $D_k = 1$, as $w_k = 1/\sigma_k^2$

Uniform weighting

- Minimize sidelobes by minimizing beam power $\|B\|^2$:

$$\frac{\partial}{\partial W_{pq}} \left[N_\ell N_m W^2 \|B\|^2 + \lambda \left(\sum_{p,q} W_{pq} - W \right) \right] = 0$$

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$$D_k = \begin{cases} \text{const} / \sum_{k \in c_{pq}} w_k & \sum_{k \in c_{pq}} w_k > 0 \\ 0 & \text{otherwise} \end{cases}$$

Robust weighting

- Find a smooth knob between natural and uniform weighting through minimization

$$V_{pq} = S + \varepsilon_{pq}$$

$$\langle \|I^D\|^2 \rangle = \frac{1}{N_\ell N_m W^2} \sum_{p,q} W_{pq}^2 (S^2 + 2\sigma_{pq}^2)$$

$$W_{pq} \propto \frac{1}{S^2 + 2\sigma_{pq}^2}$$

Briggs 1995

‘Natural’ weighting for a resolved source

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- Gaussian tapering increases SNR of resolved sources *because the taper approximates a matched filter*

$$T_k D_k w_k \propto |V_k|/\sigma_k^2$$

Briggs 1995

Generalized Briggs robust weighting

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- Minimize: $f(W) \propto \frac{1}{\text{SNR}} + \alpha \|B\|^2$

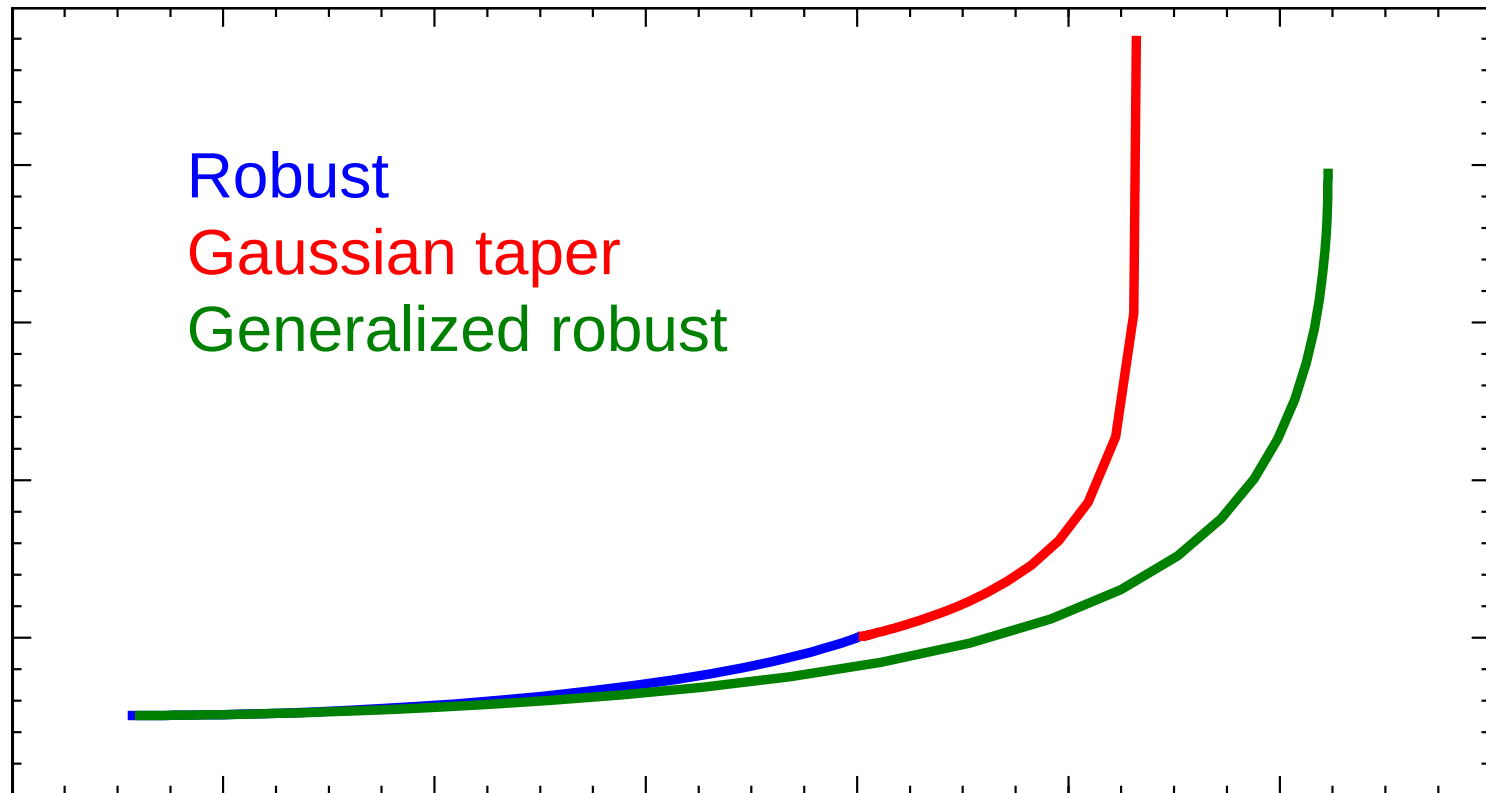
Generalized Briggs robust weighting

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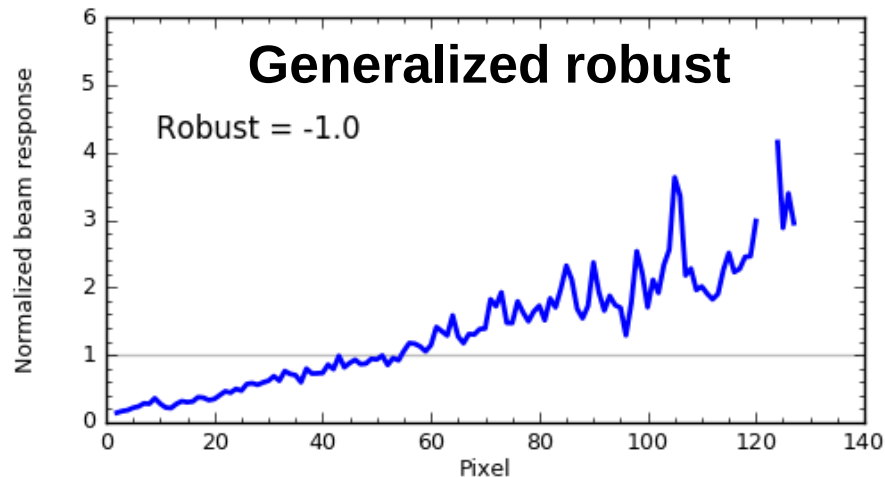
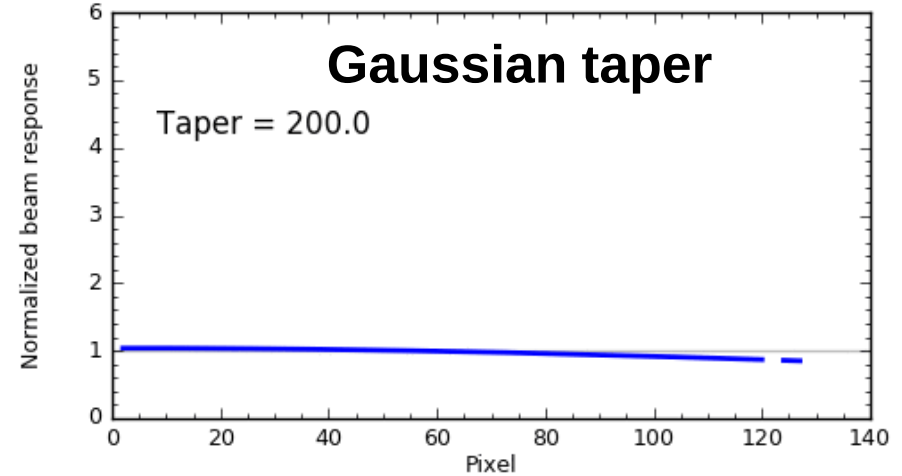
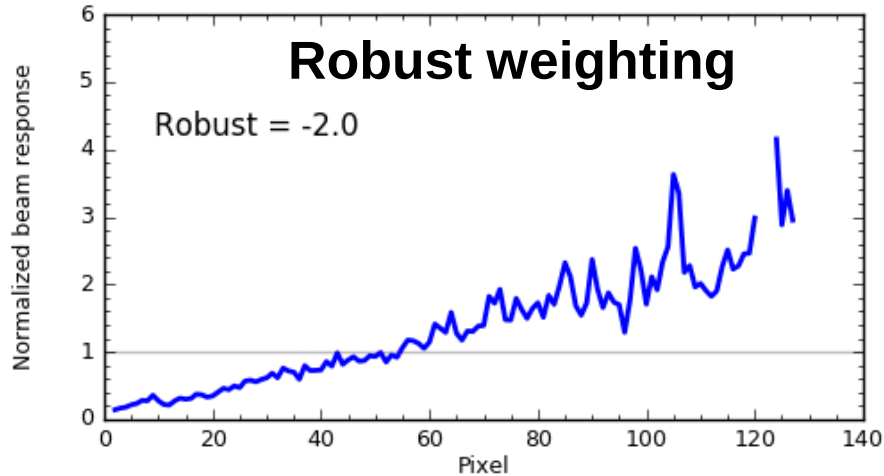
- Minimize: $f(W) \propto \frac{1}{\text{SNR}} + \alpha \|B\|^2$

- Find that:
$$W_{pq} = \frac{(5 \times 10^{-r})^2 \overline{|V_{pq}|} + |V_{pq}|}{(5 \times 10^{-r})^2 \overline{\sigma_{pq}^2} + \sigma_{pq}^2}$$

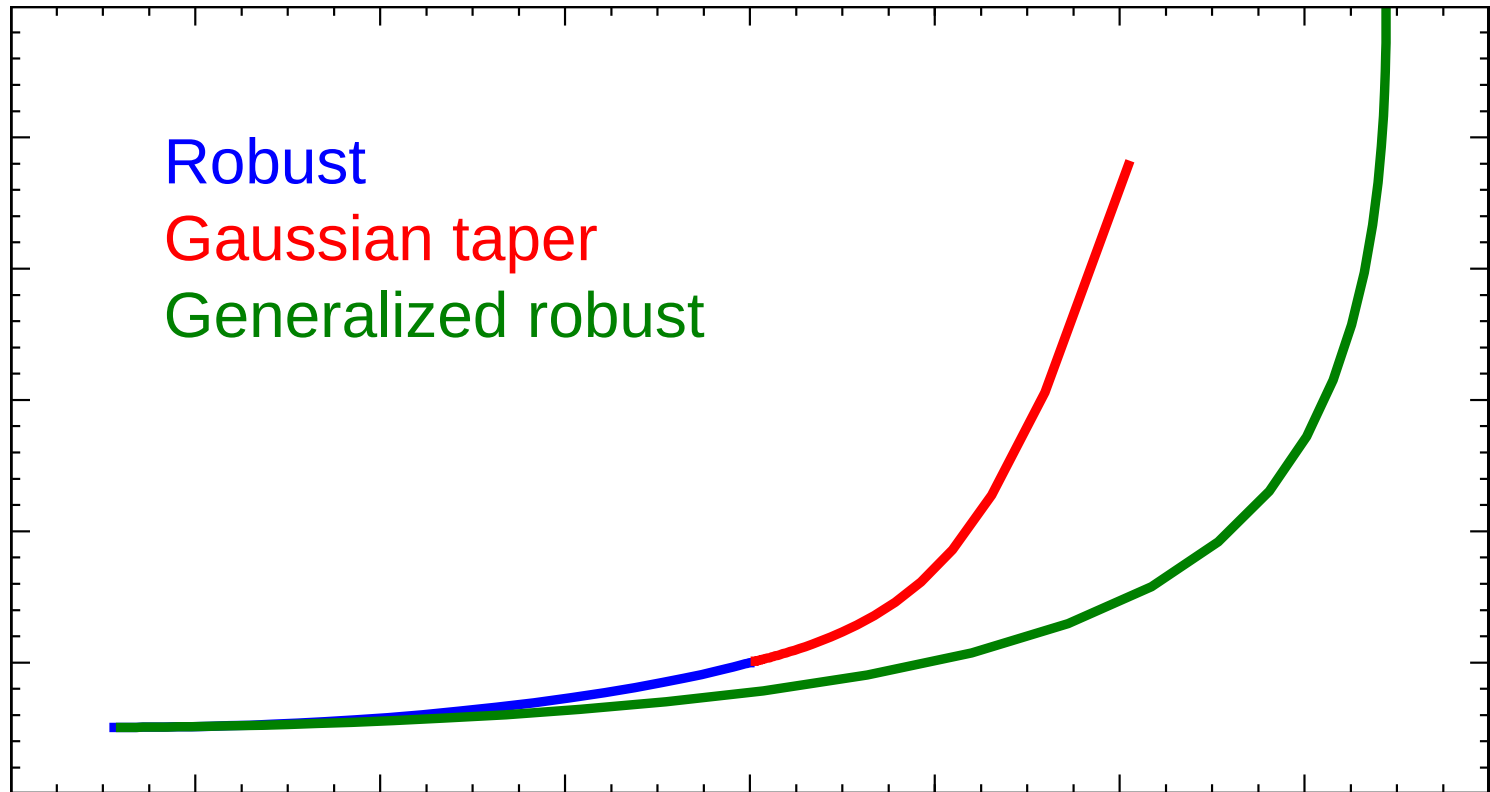
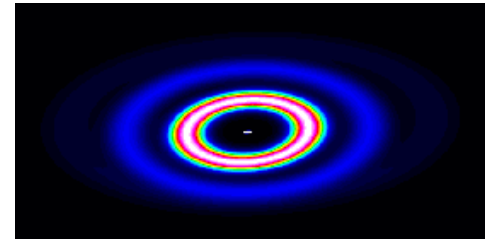
Test case - ring



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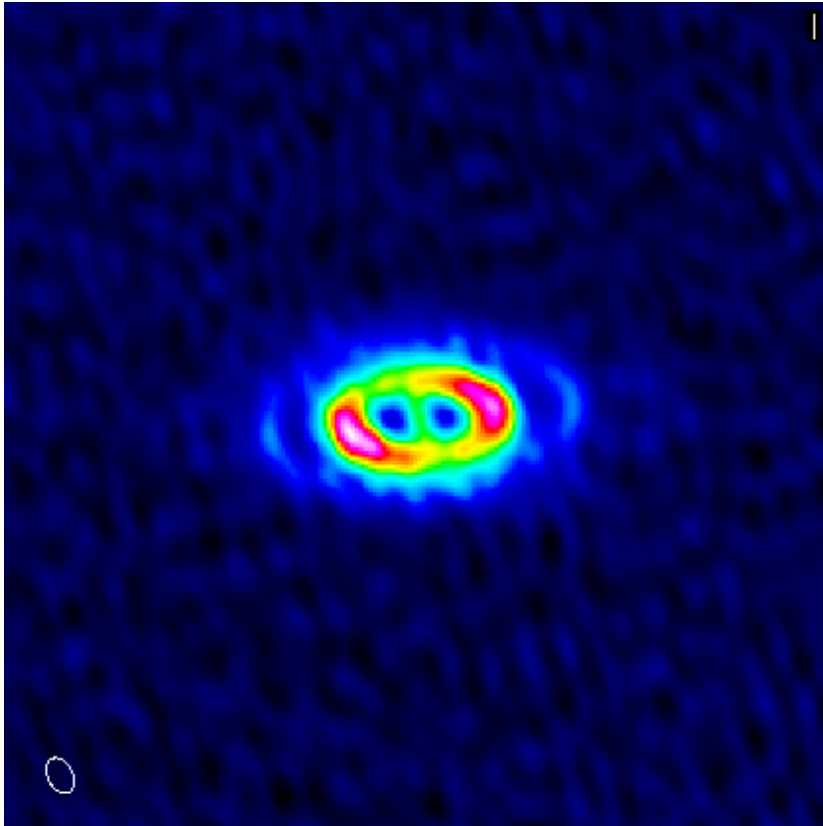


Realistic example – AA Tau



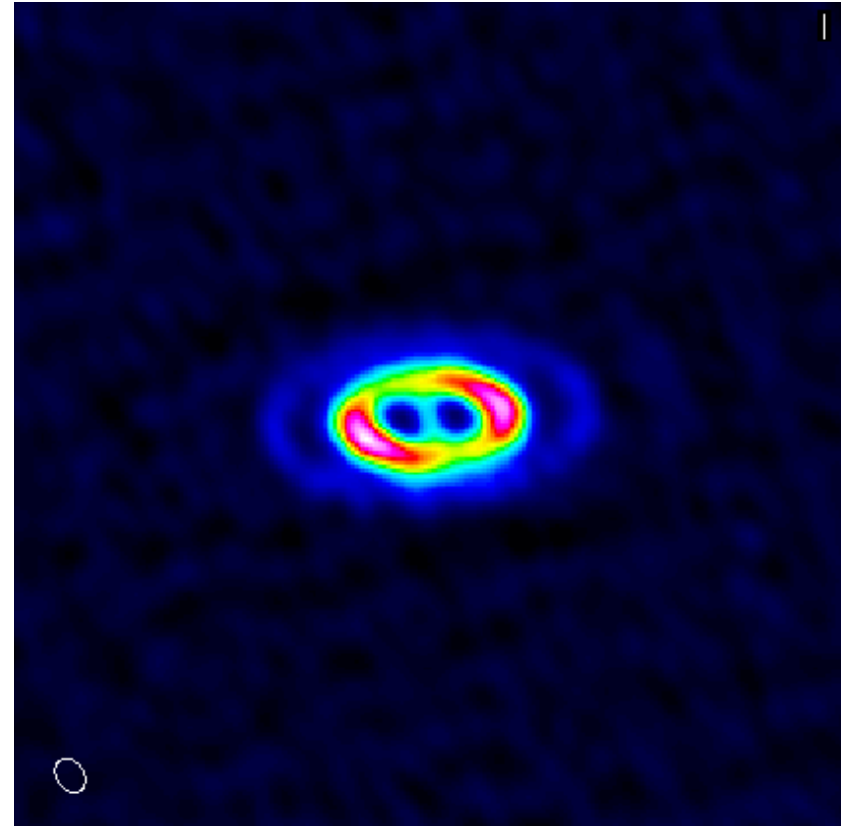
Realistic example – AA Tau

Uniform weighting



SNR = 49

Generalized Briggs



SNR = 87

Loomis + 2017

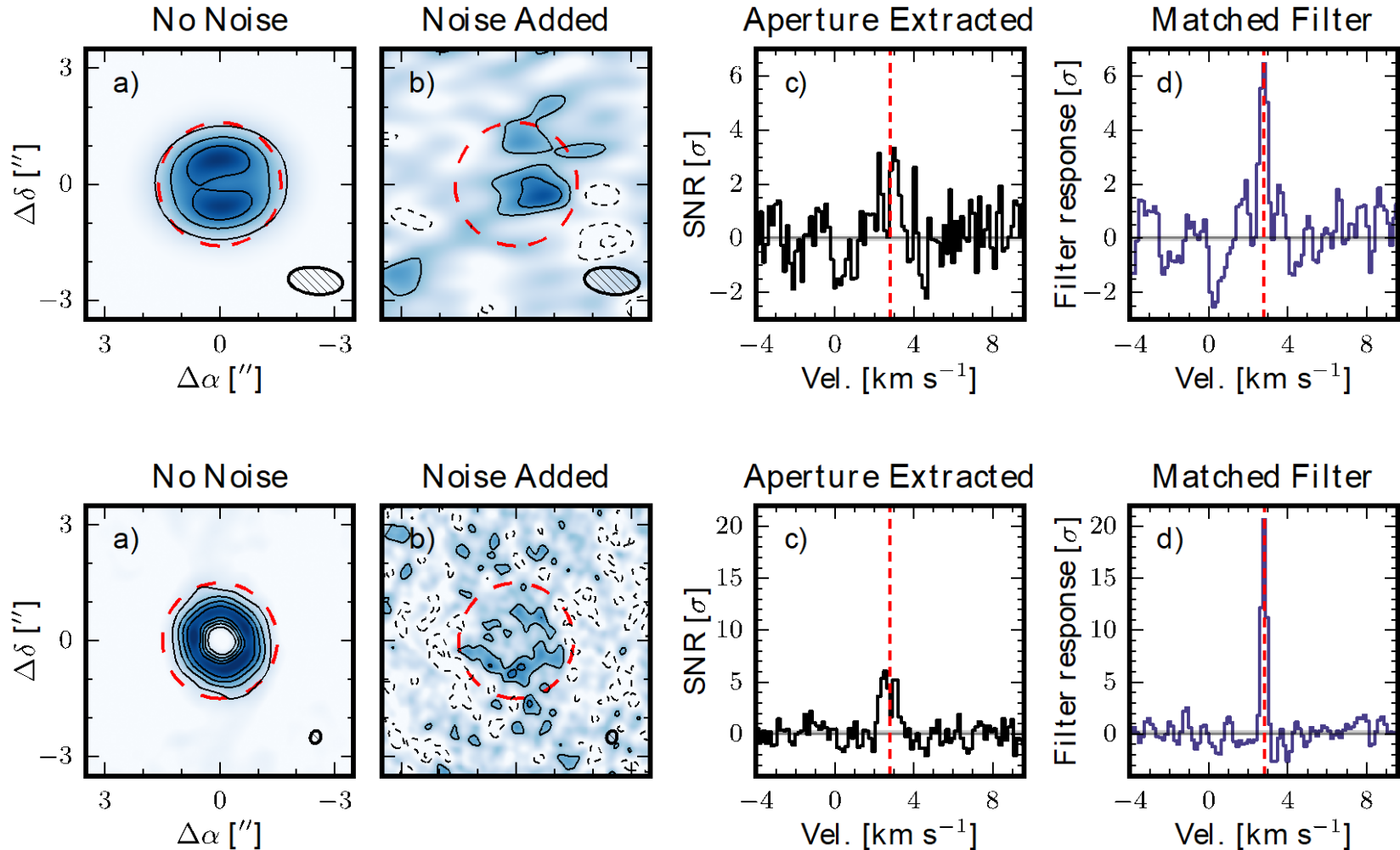
Summary

- Generalized robust weighting outperforms robust weighting for all extended sources, and reduces to robust weighting for point sources
- Especially shines in comparison to tapering, good for cases where you need a little extra SNR, but want to preserve resolution
- Need knowledge of source structure – CLEAN model is an estimate of this!

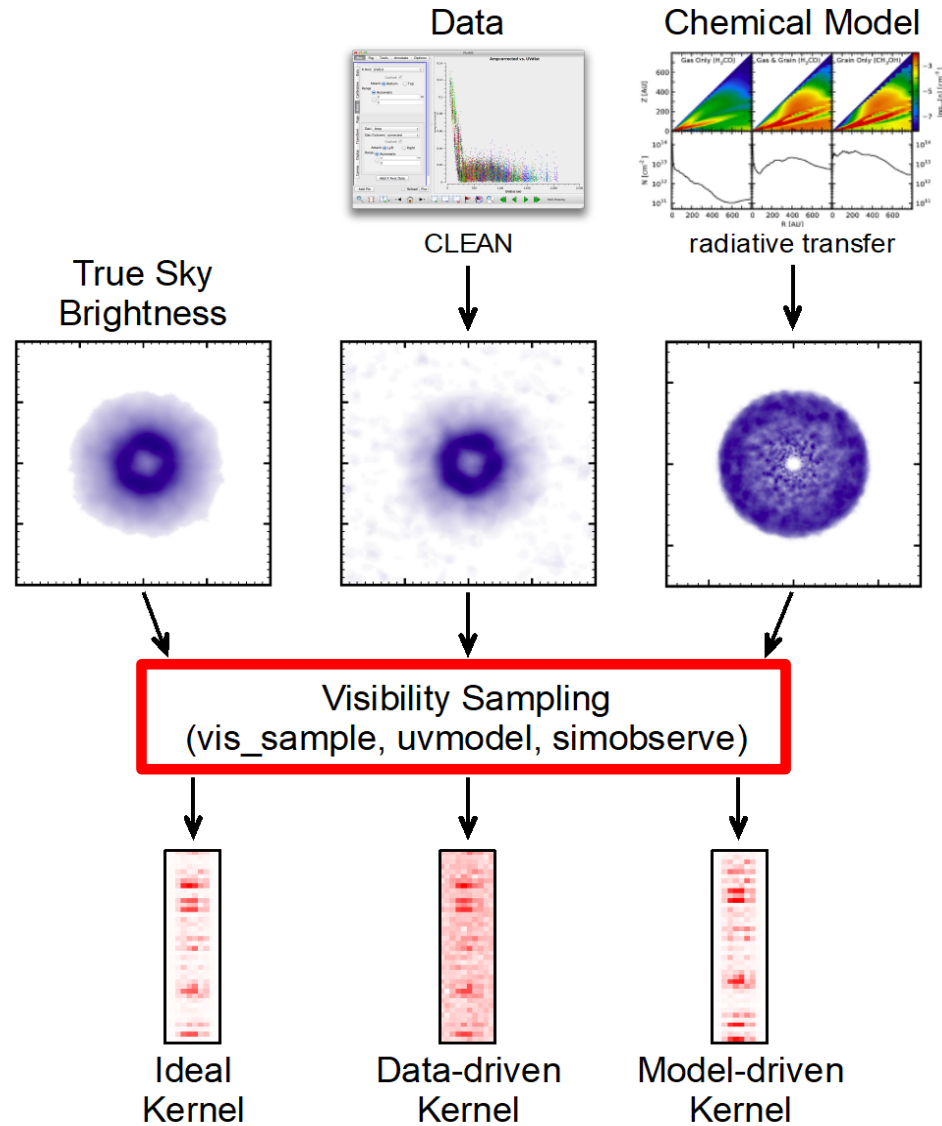
Summary

- Matched filtering allows priors to be leveraged, increasing spectral SNR and image fidelity
- Prior constraints can be derived from the data itself, or from astrophysical/chemical models
- VISIBLE tool available for use! Check it out at: github.com/AstroChem/VISIBLE
- Generalized robust weighting implemented in CASA, stay tuned for release

SNR boost is proportional to resolution



Kernel generation



vis_sample

- Python implementation of uvmodel https://github.com/AstroChem/vis_sample
- ~25% faster than uvmodel
- Accepts FITS cubes (i.e. from LIME) and RADMC-3D output files
- Interfaces with CASA measurement sets (input and output)